

# Cyber-Physical Challenges in Wide-Area Control of Power Systems

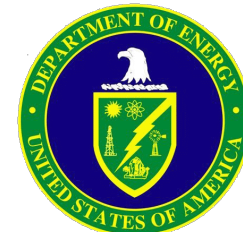
Theory, Challenges, and Open Problems

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North Carolina State University

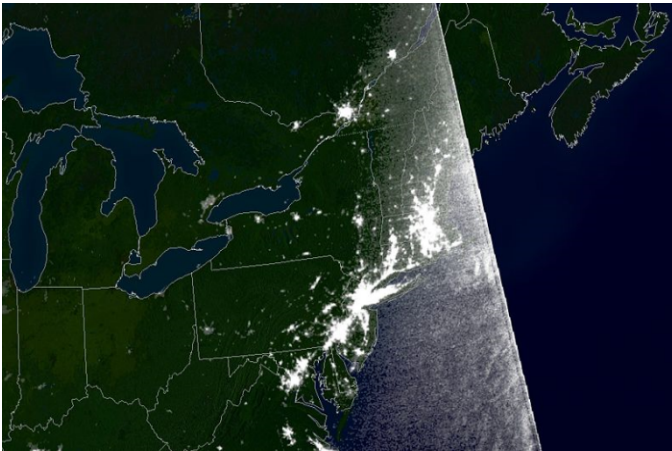
Internet2 Monthly Webinar

July 28, 2017



# Main trigger: 2003 Northeast Blackout

NYC before blackout



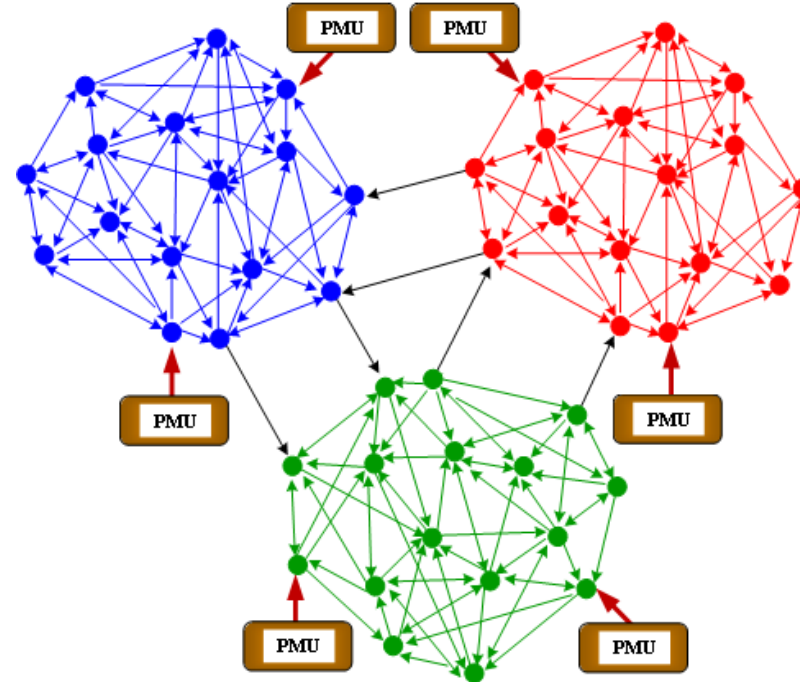
NYC after blackout



## 2 Main Lessons Learnt from the 2003 Blackout:

1. Need significantly higher resolution measurements

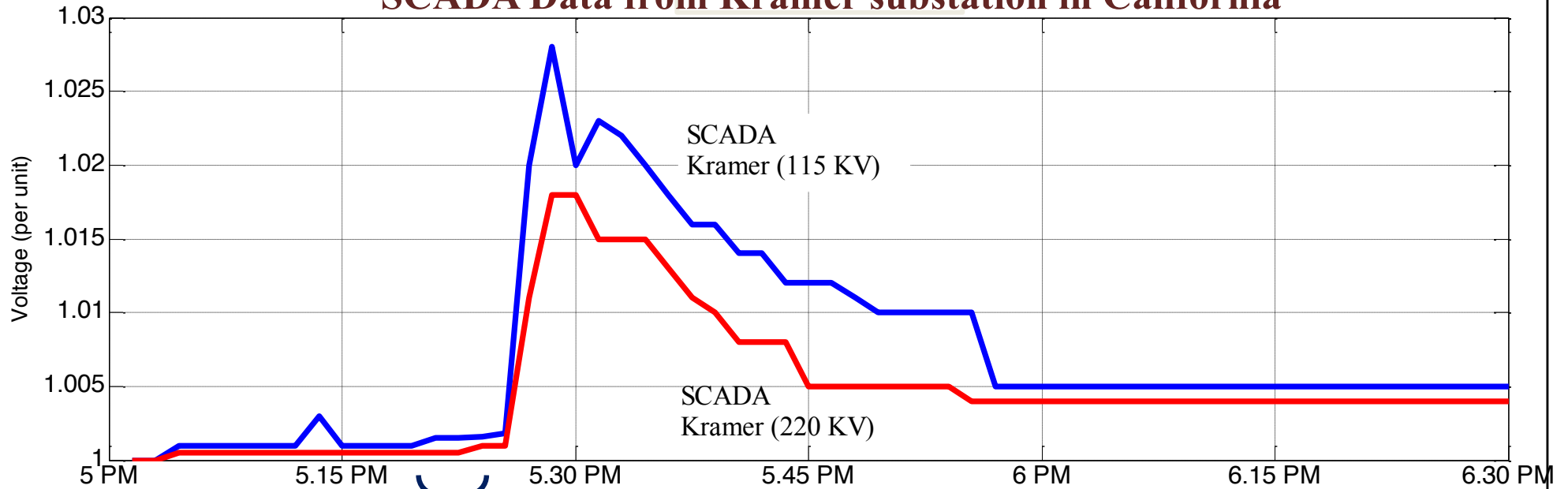
⇒ From traditional SCADA (System Control and Data Acquisition) to PMUs (Phasor Measurement Units)



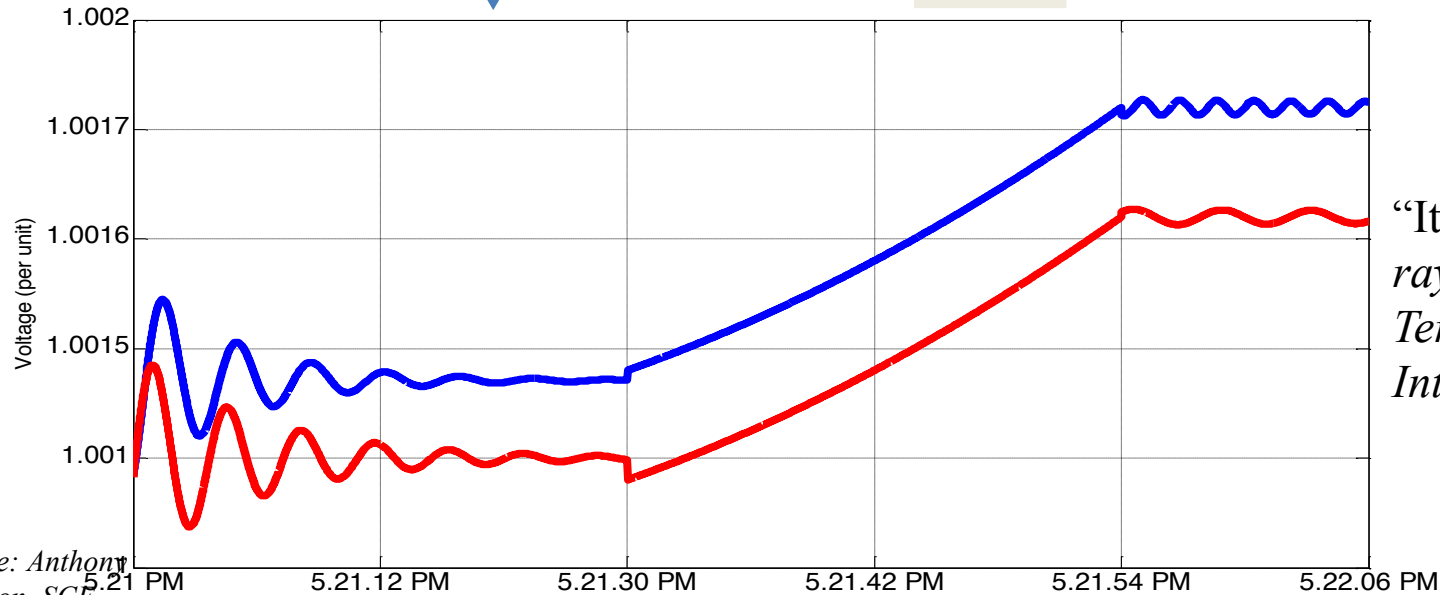
2. Local monitoring & control can lead to disastrous results

⇒ Coordinated control instead of selfish control

# SCADA Data from Kramer substation in California



## PMU Data



“It's like going from an *X-ray* to a *MRI* of the grid.”  
*Terry Boston, CEO, PJM Interconnection*

# What is a PMU (Phasor Measurement Unit)?



- PMUs are digital data-recording devices that measure and export GPS-synchronized, high sampling rate (6-120 samples/sec) dynamic measurements of phase angles, voltages, currents and frequency
- Developed by Arun Phadke (VA Tech) and Jim Thorp (Cornell Univ.) in the 1980s.

## 3 Development

Subsequent Testing on the AEP Model Power System



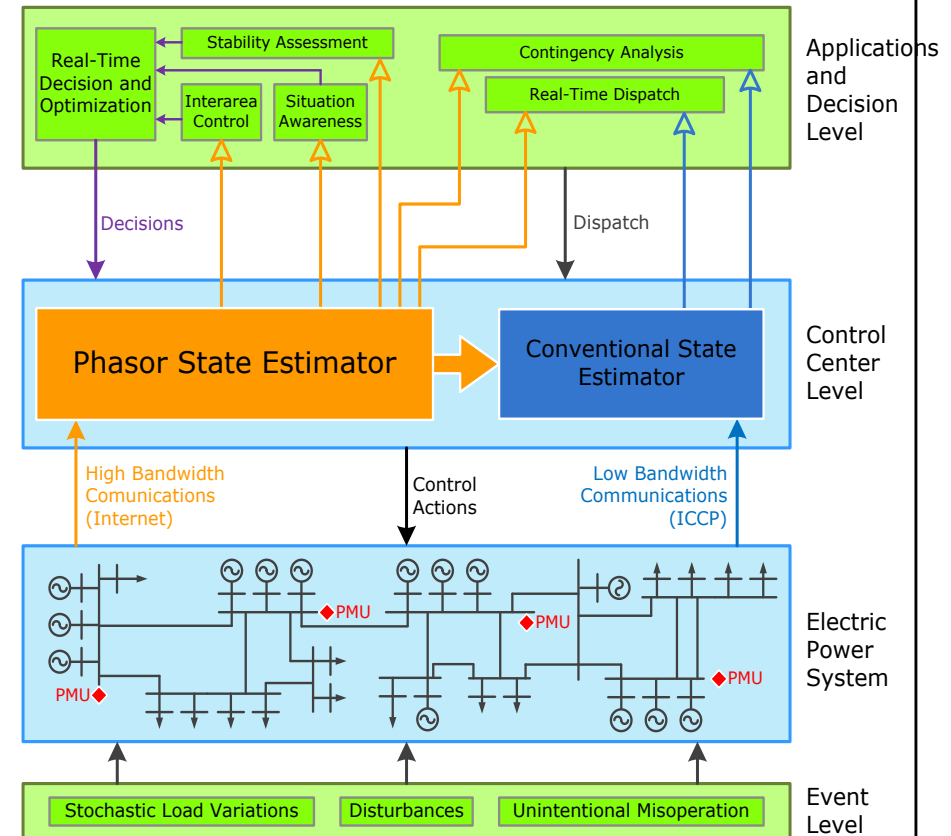
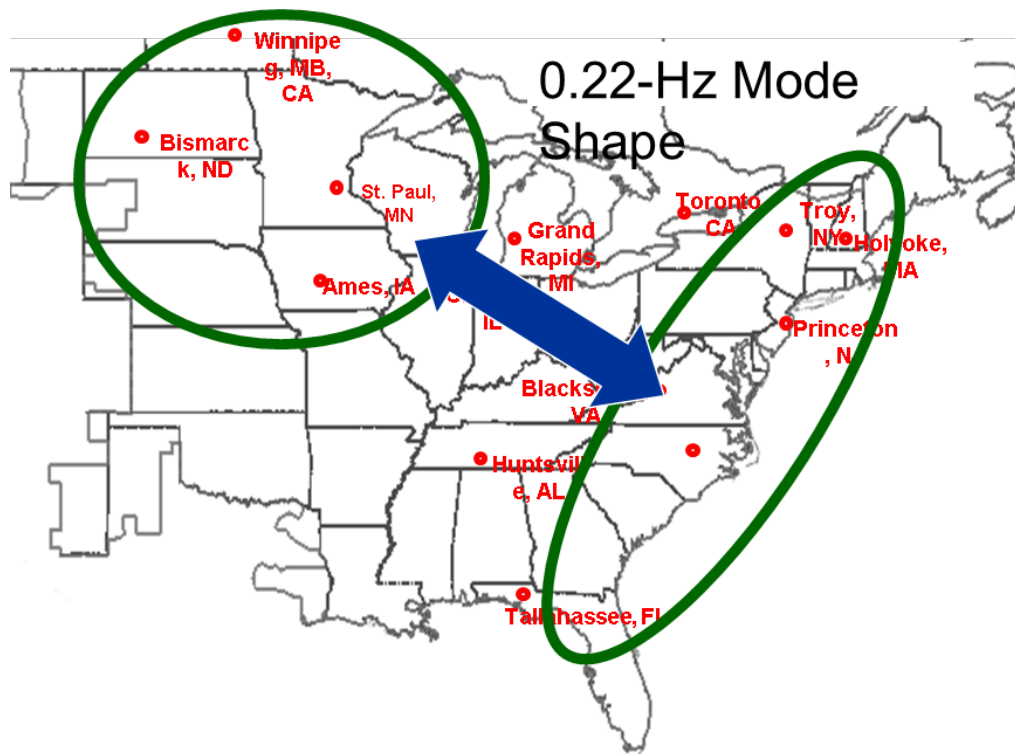
# Applications so far

## 1. Oscillation Monitoring Algorithms

- 1.1 Mode meter – PNNL
- 1.2 Real-time monitor – WSU, BPA
- 1.3 Ringdown & ambient – UW, MTU
- 1.4 Predictive models – RPI, NCSU, Imperial
- 1.5 Mode shapes – WSU, KTH, SCE
- 1.6 Voltage stability – ABB, SCE, Quanta

## 2. Phasor State Estimator

- 2.1 Three-phase PSE – VA Tech, Dominion
- 2.2 PMU placement algorithms – NEU, RPI
- 2.3 Bad data detectors – NEU, RPI, ISO-NE
- 2.4 Dynamic PSE – VA Tech, PNNL
- 2.5 PSE installations - CURENT

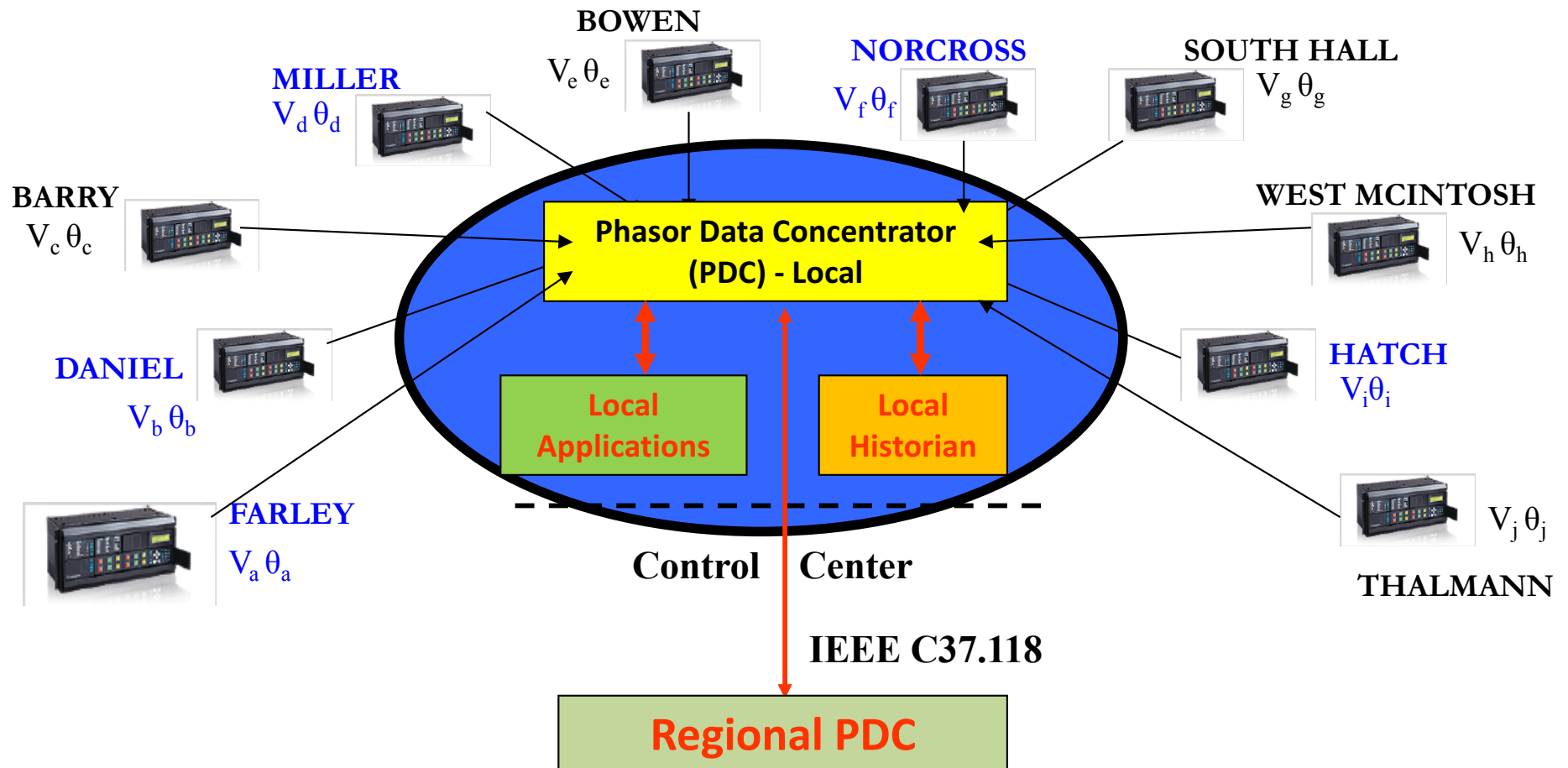


Source: Dan Trudnowski, Joe H. Chow

# WAMS Architecture

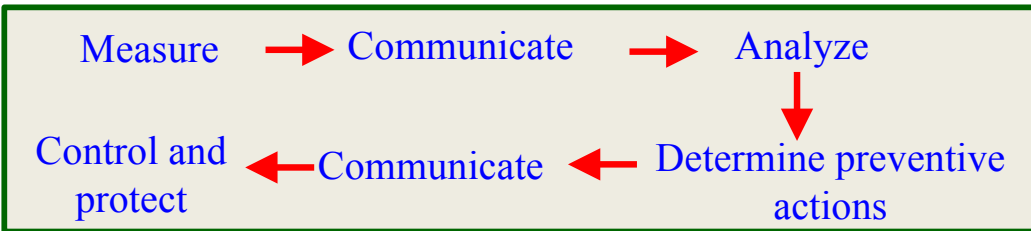
- Mostly centralized sensing + computing architecture

## WAMS architecture of Southern Company, GA



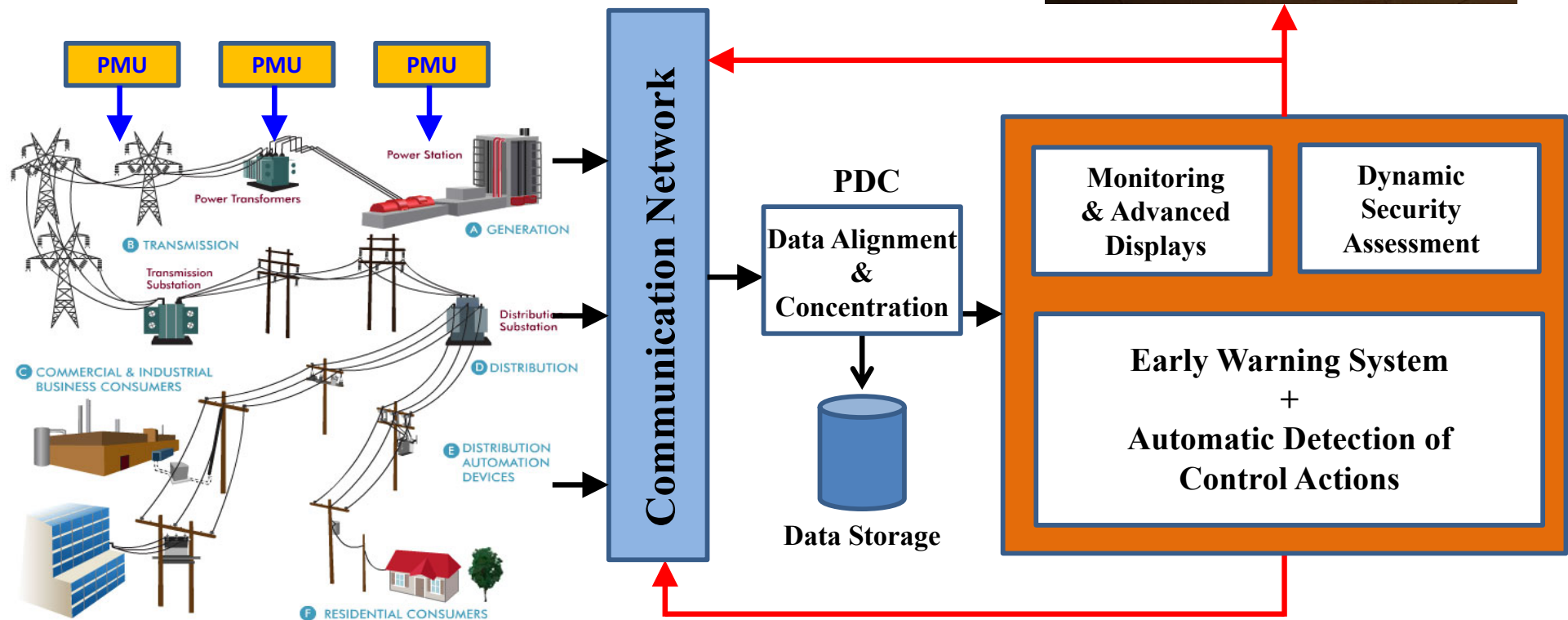
# Architectures for Wide-Area Control

## Scenario 1: Human-in-the-loop control



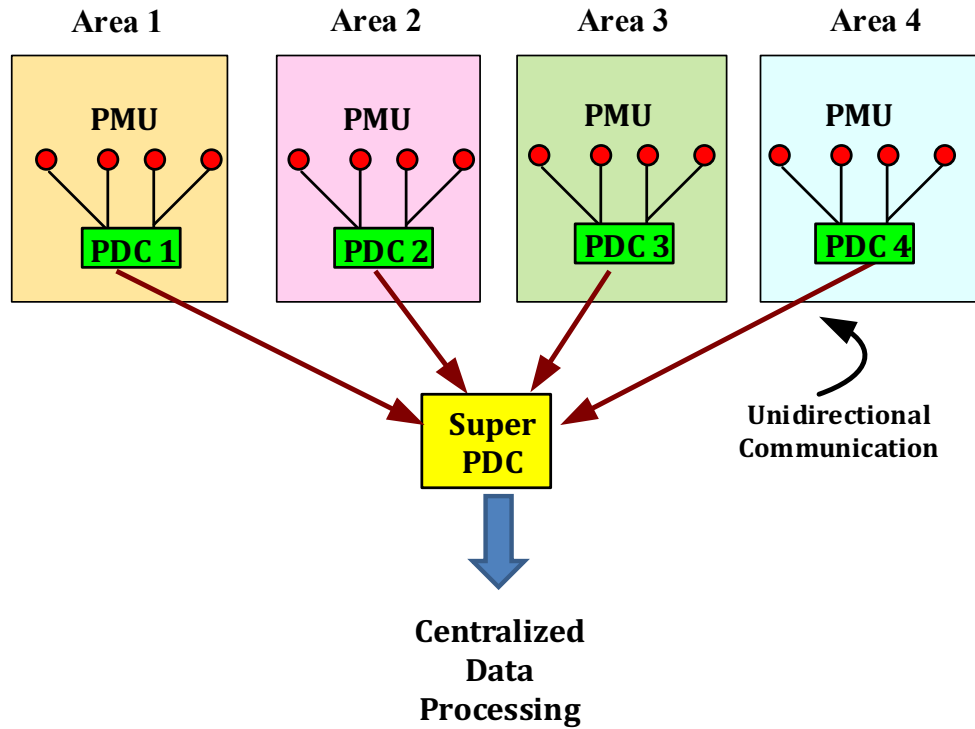
Examples: Wide-area protection, cascading failure control, wide-area AGC

Transmission System Control Room



# Centralized vs Distributed Architectures

## Centralized WAMS

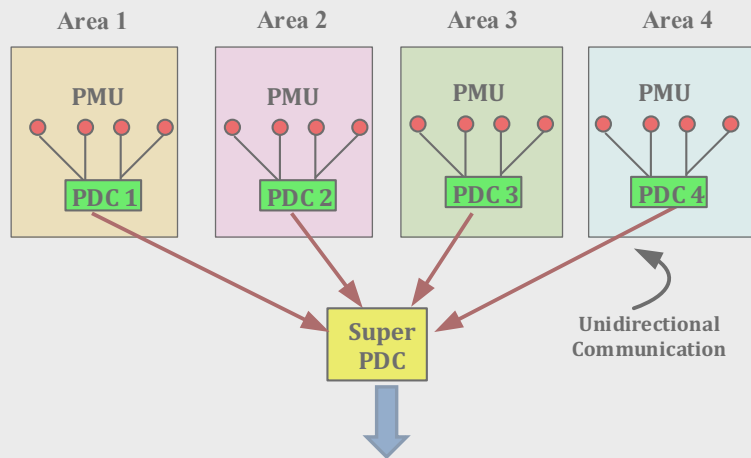


**Control Room**



# Centralized vs Distributed Algorithms

## Centralized WAMS

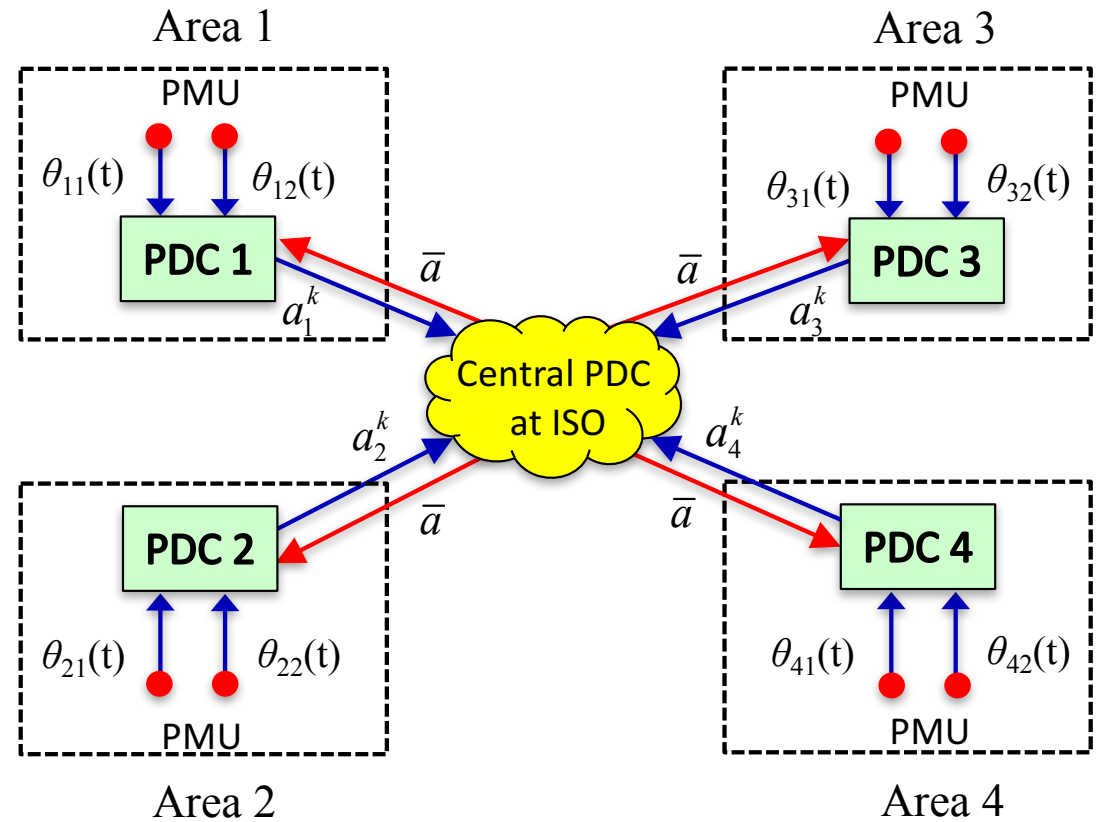


Centralized  
Data  
Processing



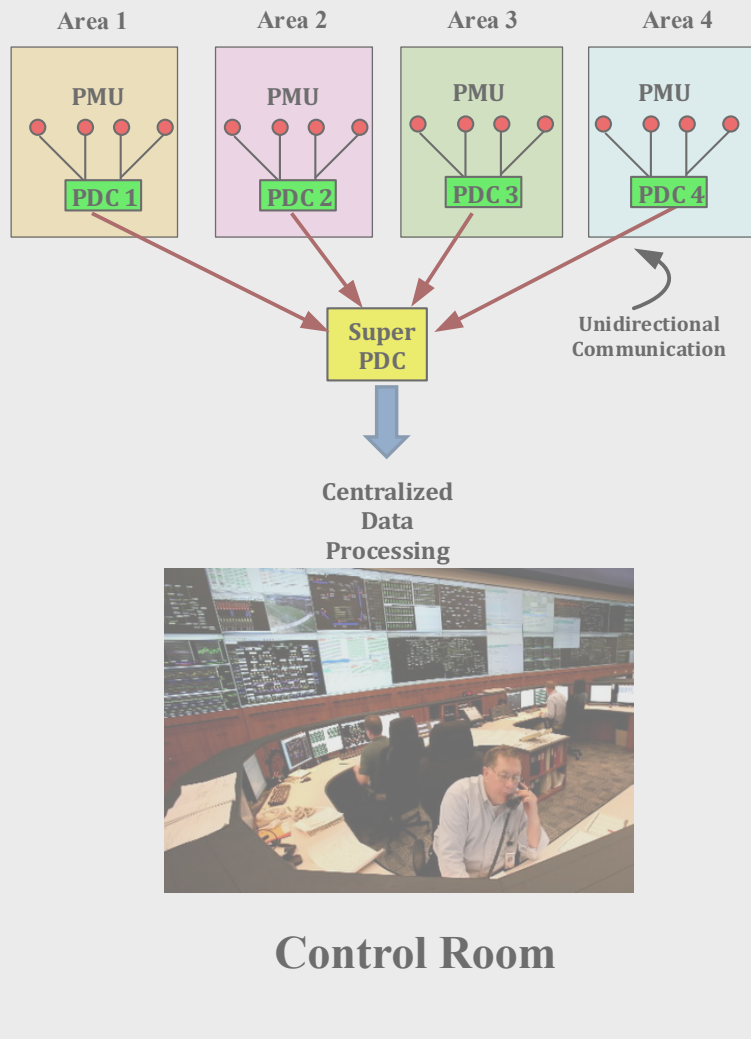
Control Room

## Semi-Distributed WAMS

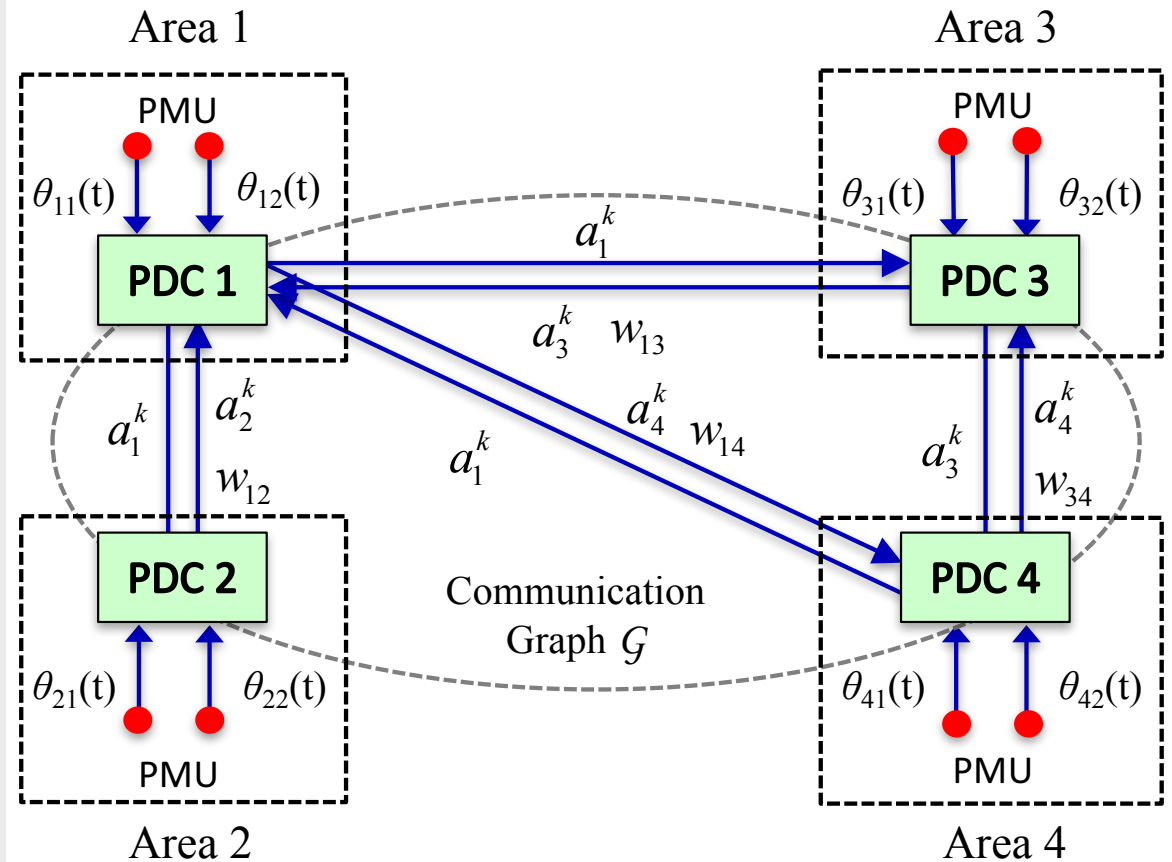


# Centralized vs Distributed Algorithms

## Centralized WAMS

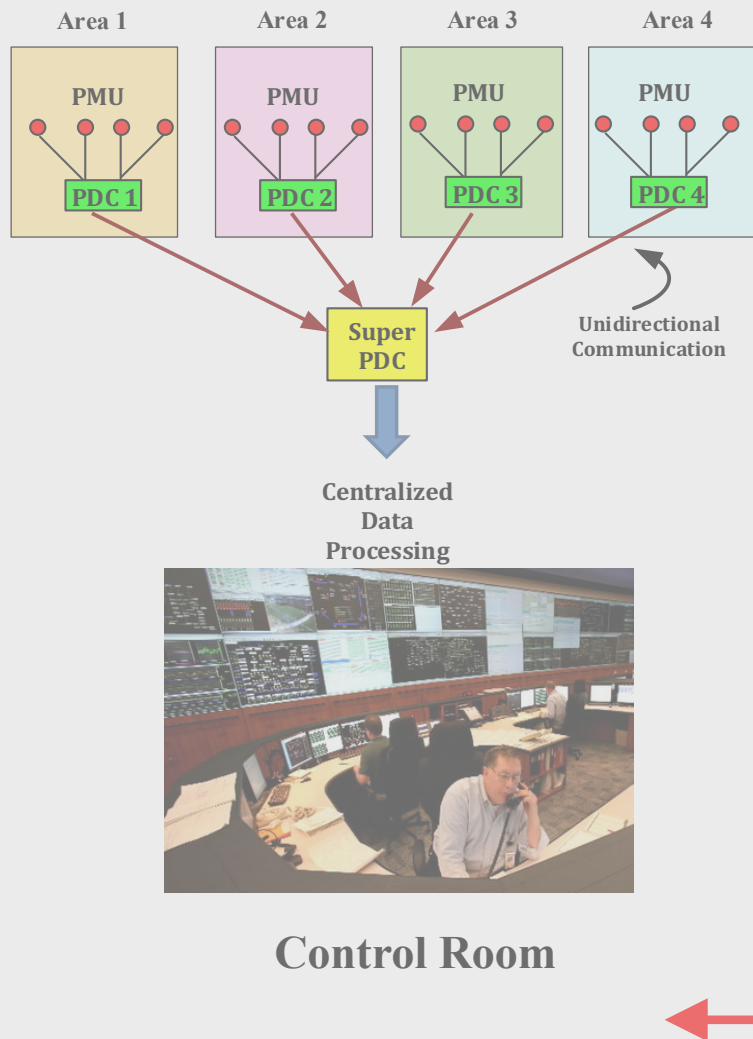


## Distributed WAMS

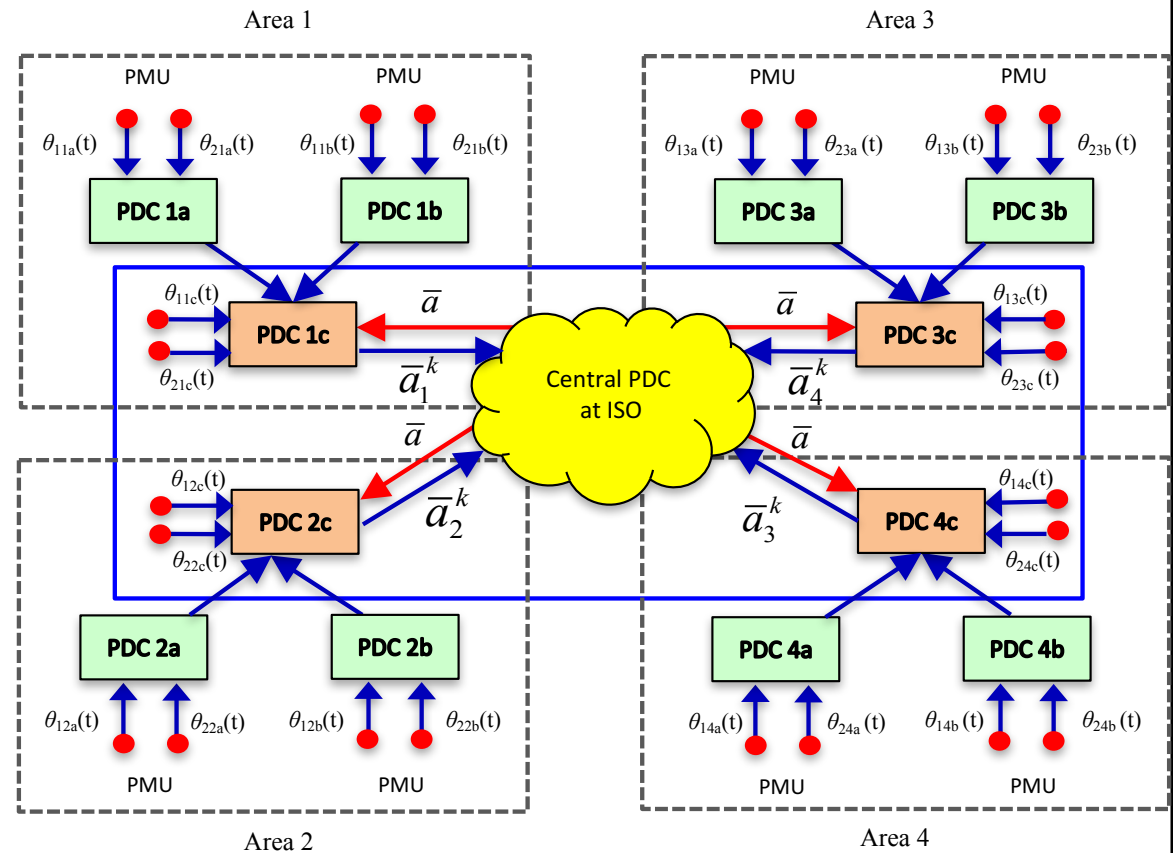


# Centralized vs Distributed Algorithms

## Centralized WAMS



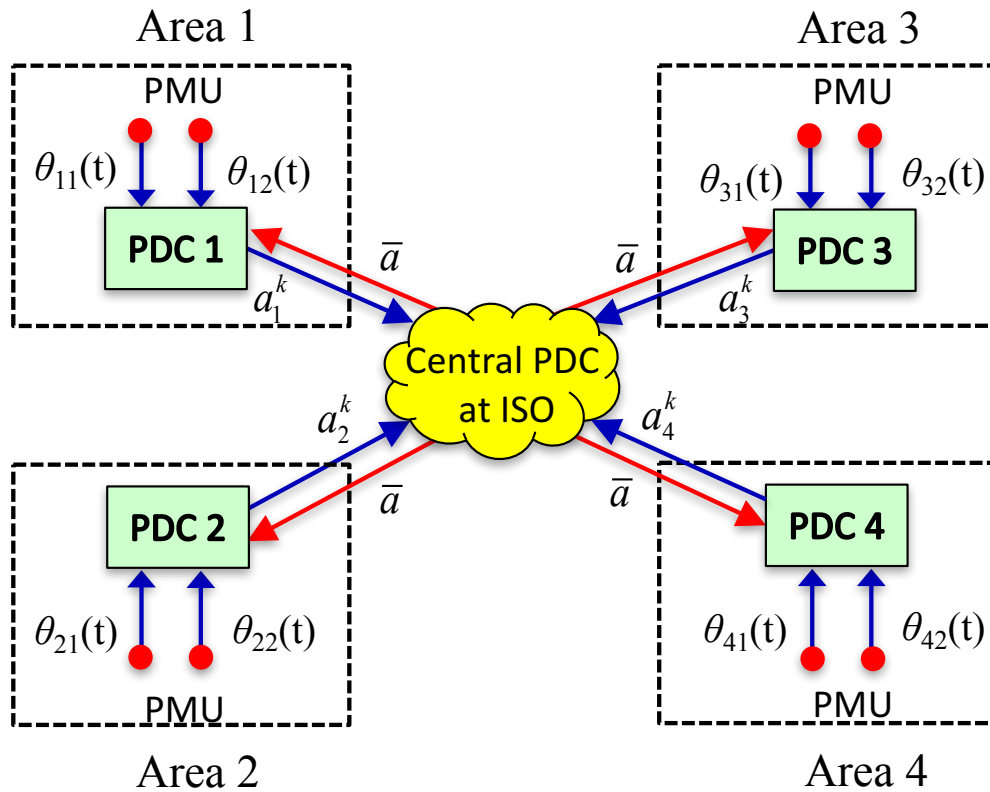
## Heirarchically Distributed



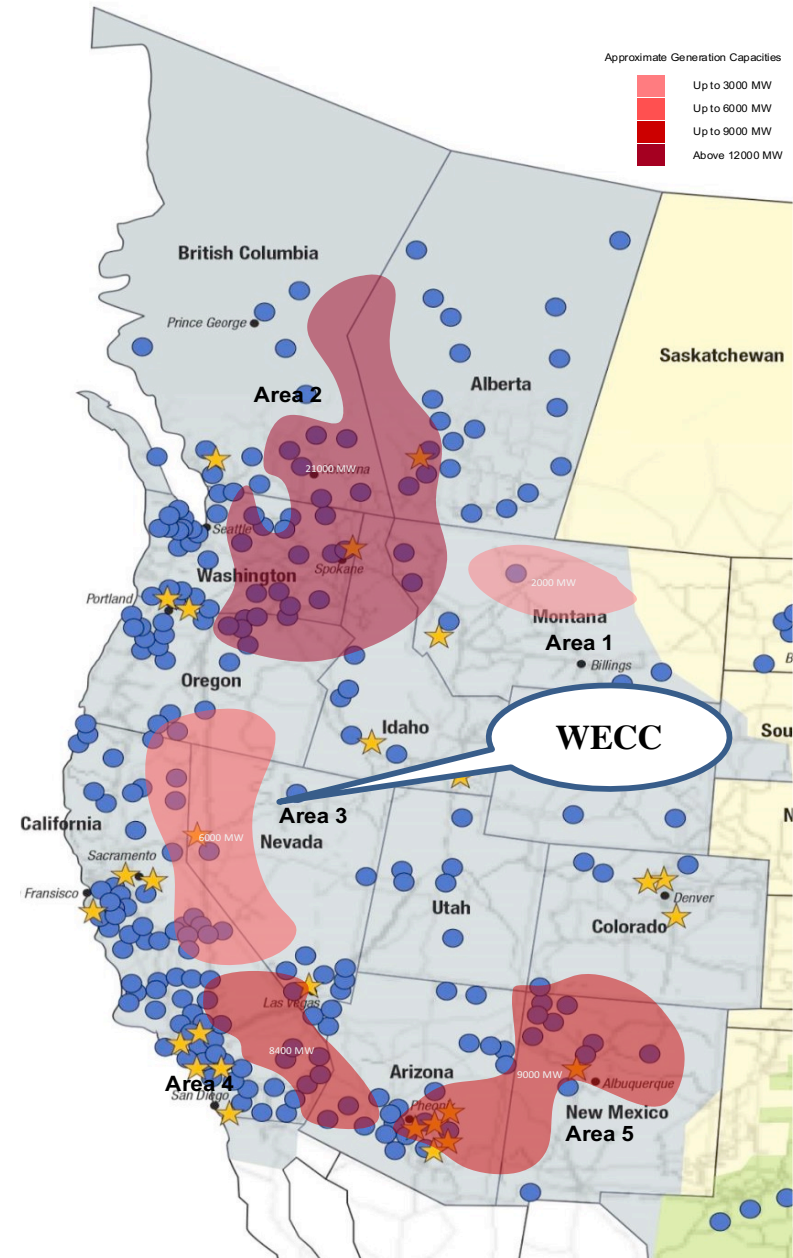
Specific application of interest for this talk:  
**Wide-area oscillation monitoring**

# Semi-Distributed Architecture

## Semi-Distributed WAMS

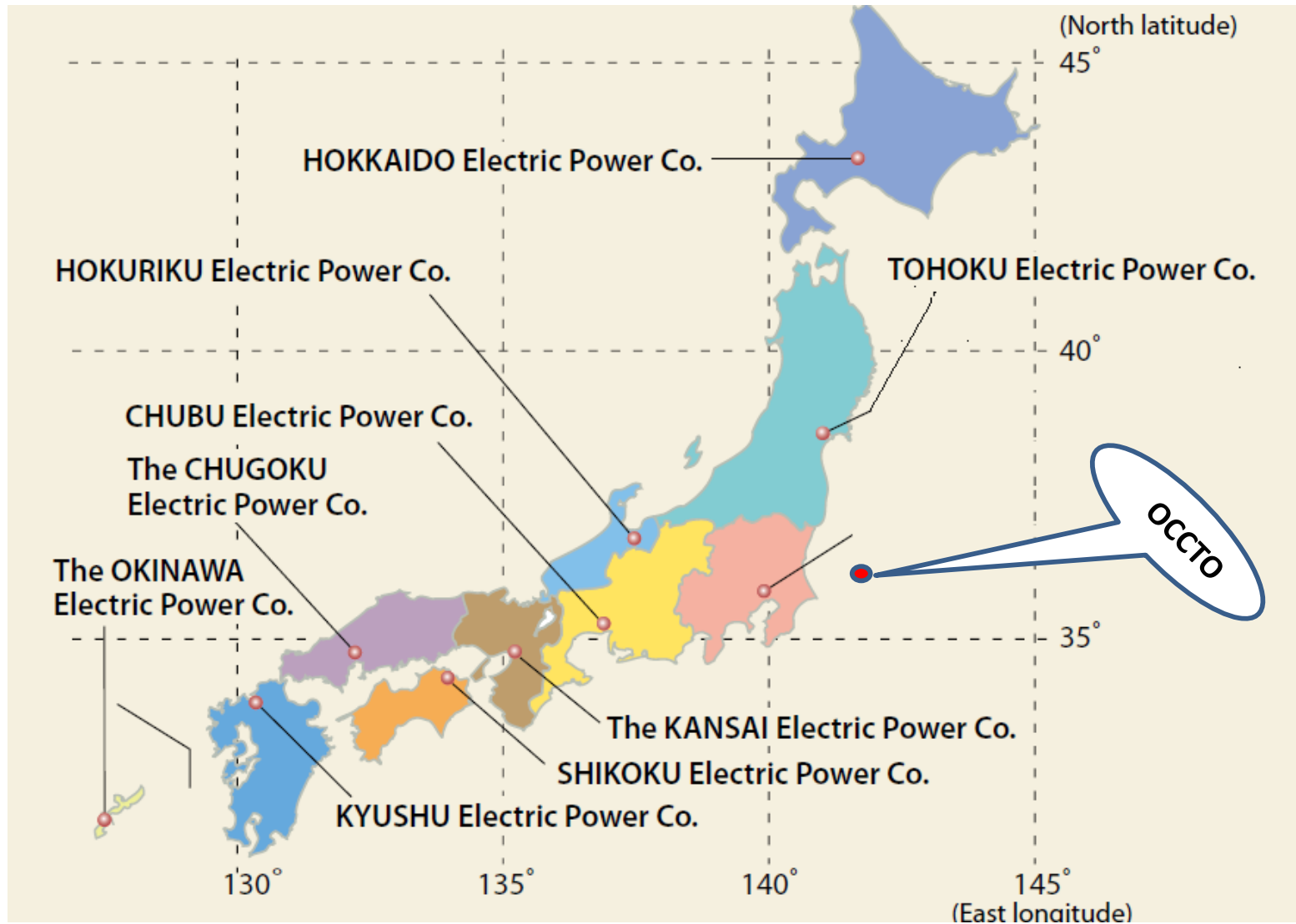


## Example: US west coast

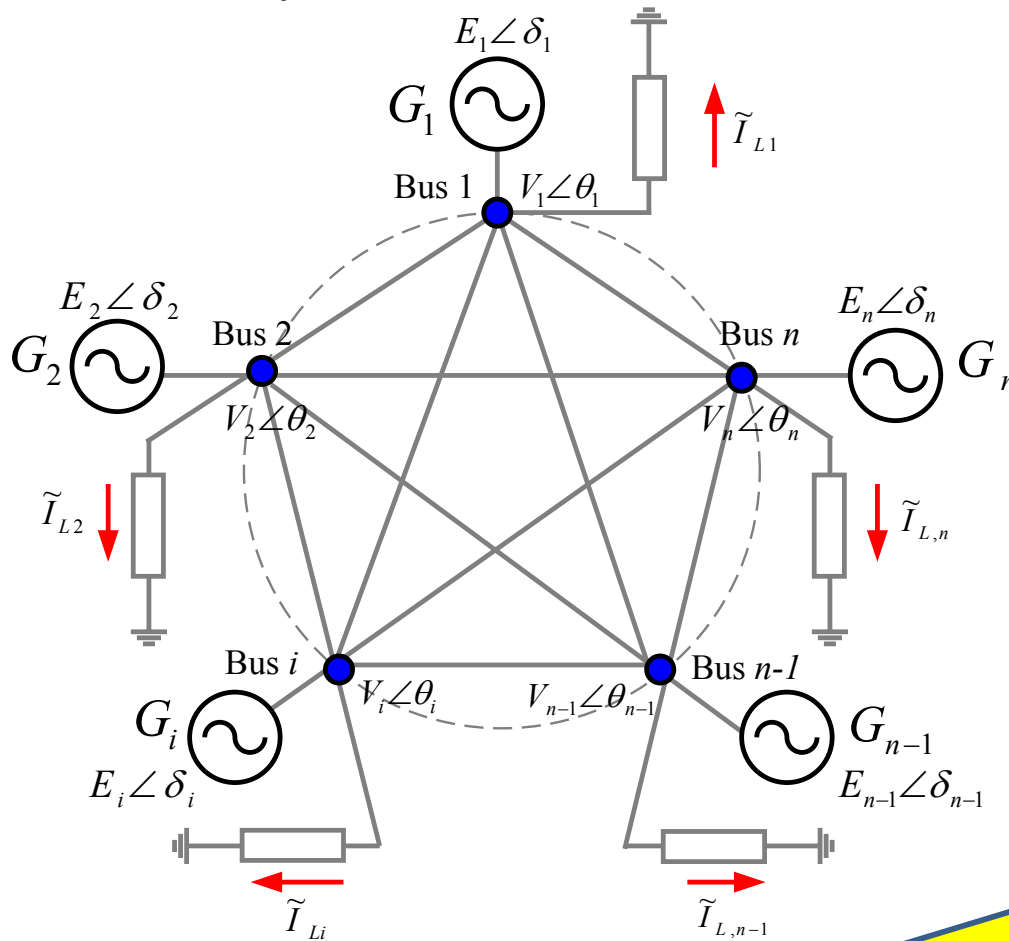


# Semi-Distributed Architecture

## Example: Japanese power grid



# Power System Model



## Measured variables from PMUs

$$y = \text{col}_{i \in \mathcal{S}}(\Delta V_i, \Delta \theta_i).$$

Voltages, currents, and phase angles at different points in the grid

Recall Differential Equations from Calculus!

## Swing equation model:

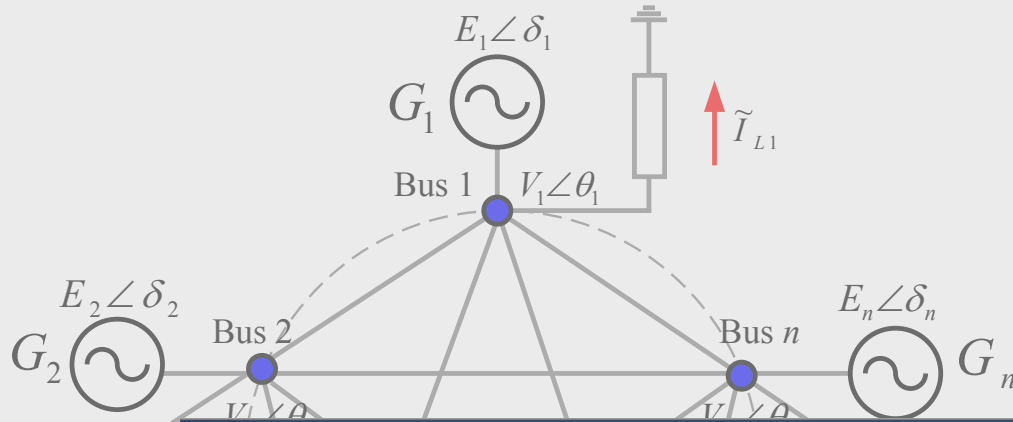
$$\begin{bmatrix} \Delta \dot{\delta} \\ M \Delta \dot{\omega} \\ \Delta \dot{E} \end{bmatrix} = \begin{bmatrix} 0 & I & 0 \\ -L(G) & -D & -P \\ K & 0 & J \end{bmatrix} \begin{bmatrix} \Delta \delta \\ \Delta \omega \\ \Delta E \end{bmatrix} + \underbrace{\begin{bmatrix} 0 \\ \text{col}_{i=1(1)n}(\gamma_i) \\ \text{col}_{i=1(1)n}(\rho_i) \end{bmatrix}}_{\text{due to load}} + \begin{bmatrix} 0 & 0 \\ 0 & I \\ I & 0 \end{bmatrix} \begin{bmatrix} \Delta P_m \\ \Delta E_F \end{bmatrix}$$

$L(G)$  = fully connected network graph

due to load

Controllable inputs

# Wide-Area Oscillation Estimation



## Output Equation

$$y = \text{col}_{i \in \mathcal{S}}(\Delta V_i, \Delta \theta_i).$$



Swing

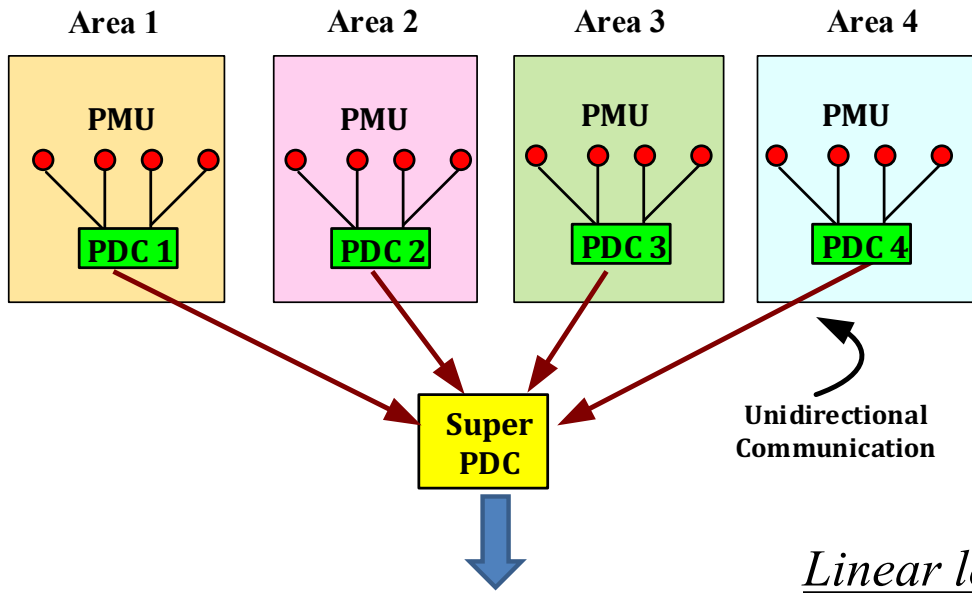
$$\begin{bmatrix} \Delta \dot{\delta} \\ M \Delta \dot{\omega} \\ \Delta \dot{E} \end{bmatrix}$$

$L(G) =$  fully connected network graph

due to load

# Wide-Area Oscillation Estimation

## Centralized:



- After the fault, wait for a few number of samples for the zero dynamics to die down
- Construct current output vector  $c$ , matrix of past samples  $H$

*Linear least squares problem:*

vectors of measurements from all areas

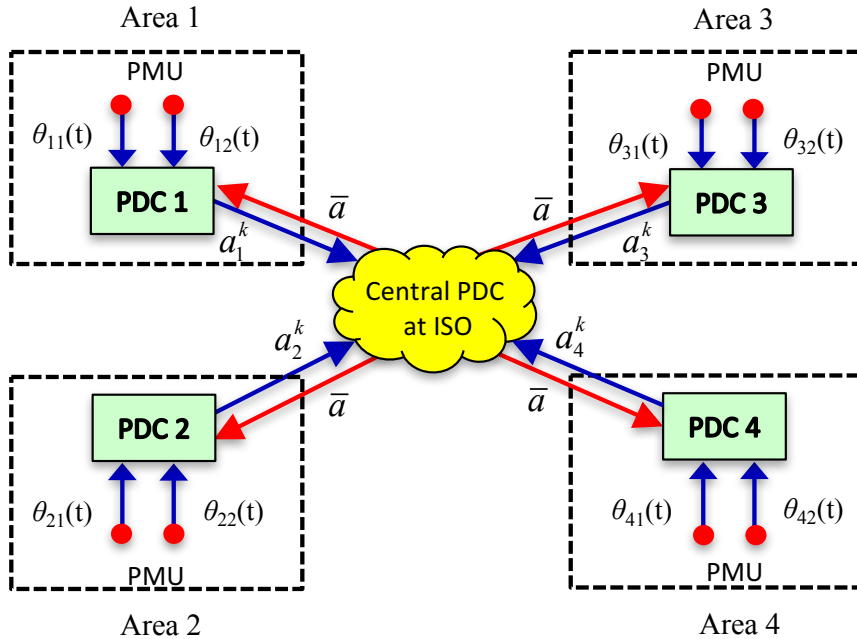
$$\begin{bmatrix} y(2n) \\ y(2n+1) \\ \vdots \\ y(2n+l) \end{bmatrix}_c = \underbrace{\begin{bmatrix} y(2n-1) & \cdots & y(0) \\ \vdots & \ddots & \vdots \\ y(2n-1+l) & \cdots & y(l) \end{bmatrix}}_H \underbrace{\begin{bmatrix} -a_1 \\ -a_2 \\ \vdots \\ -a_n \end{bmatrix}}_a$$

$$\hat{a} = \arg \min_a \|Ha - c\|^2$$



# Wide-Area Oscillation Estimation

## Distributed:



## Multiple Computational Areas

$$\text{Area 1: } \hat{\theta}_1 = \{\theta_{30}, \theta_{66}\} \rightarrow (\hat{H}_1 = \begin{bmatrix} H_{30} \\ H_{66} \end{bmatrix}, \hat{\mathbf{c}}_1 = \begin{bmatrix} \mathbf{c}_{30} \\ \mathbf{c}_{66} \end{bmatrix})$$

$$\text{Area 2: } \hat{\theta}_2 = \{\theta_{16}, \theta_{53}\} \rightarrow (\hat{H}_2 = \begin{bmatrix} H_{16} \\ H_{53} \end{bmatrix}, \hat{\mathbf{c}}_2 = \begin{bmatrix} \mathbf{c}_{16} \\ \mathbf{c}_{53} \end{bmatrix})$$

$$\text{Area 3: } \hat{\theta}_3 = \{\theta_{68}\} \rightarrow (\hat{H}_3 = H_{68}, \hat{\mathbf{c}}_3 = \mathbf{c}_{68})$$

$$\text{Area 4: } \hat{\theta}_4 = \{\theta_{56}\} \rightarrow (\hat{H}_4 = H_{56}, \hat{\mathbf{c}}_4 = \mathbf{c}_{56})$$

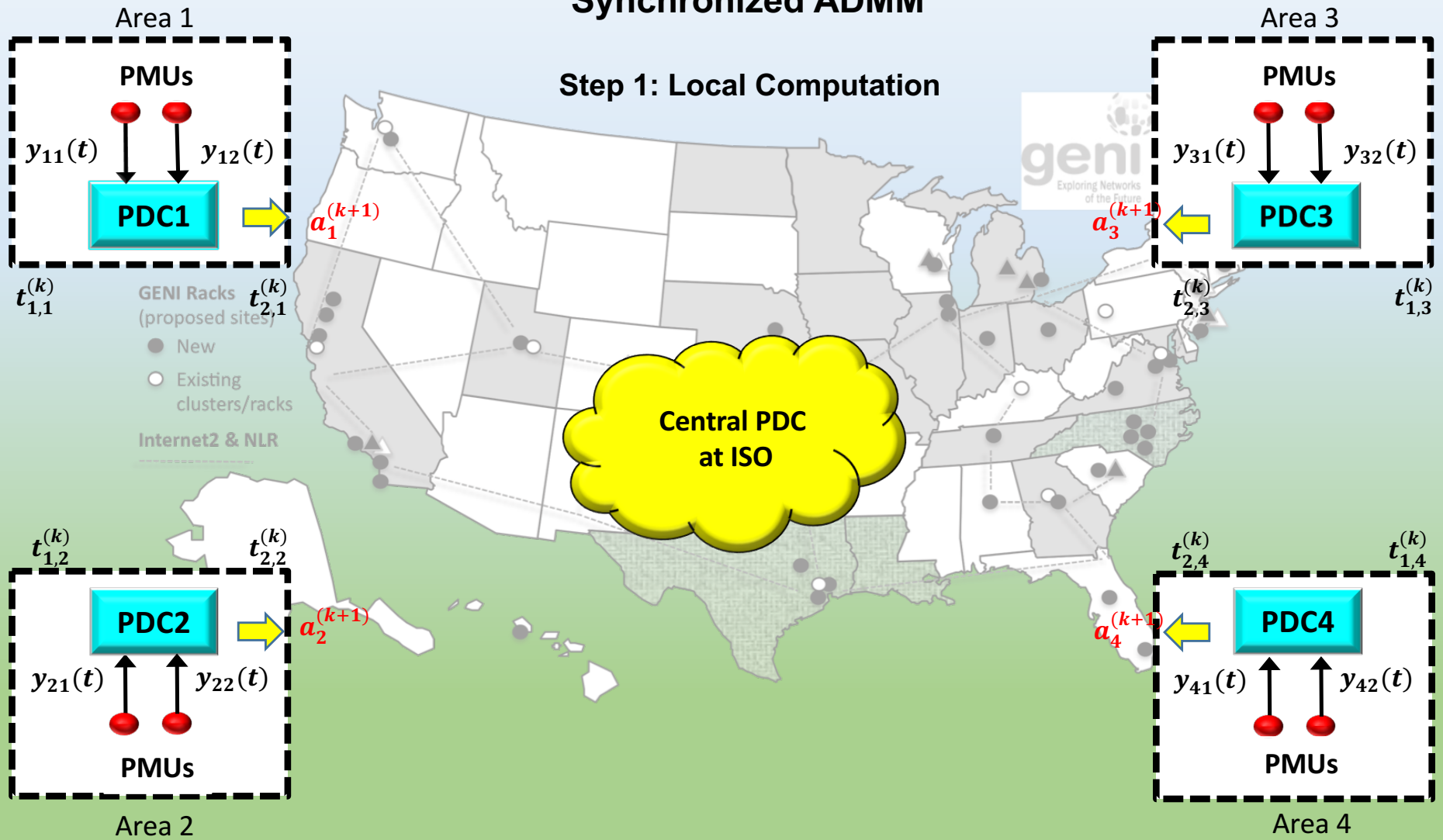
## Global Consensus Problem:

$$\begin{aligned} & \underset{\mathbf{a}_1, \mathbf{a}_2, \dots, \mathbf{a}_N, \mathbf{z}}{\text{minimize}} \sum_{i=1}^N \frac{1}{2} \left\| \hat{H}_i \mathbf{a}_i - \hat{\mathbf{c}}_i \right\|_2^2 \\ & \text{subject to } \mathbf{a}_i - \mathbf{z} = 0, \text{ for } i = 1, \dots, N \end{aligned}$$

Solve the above optimization problem in a distributed way

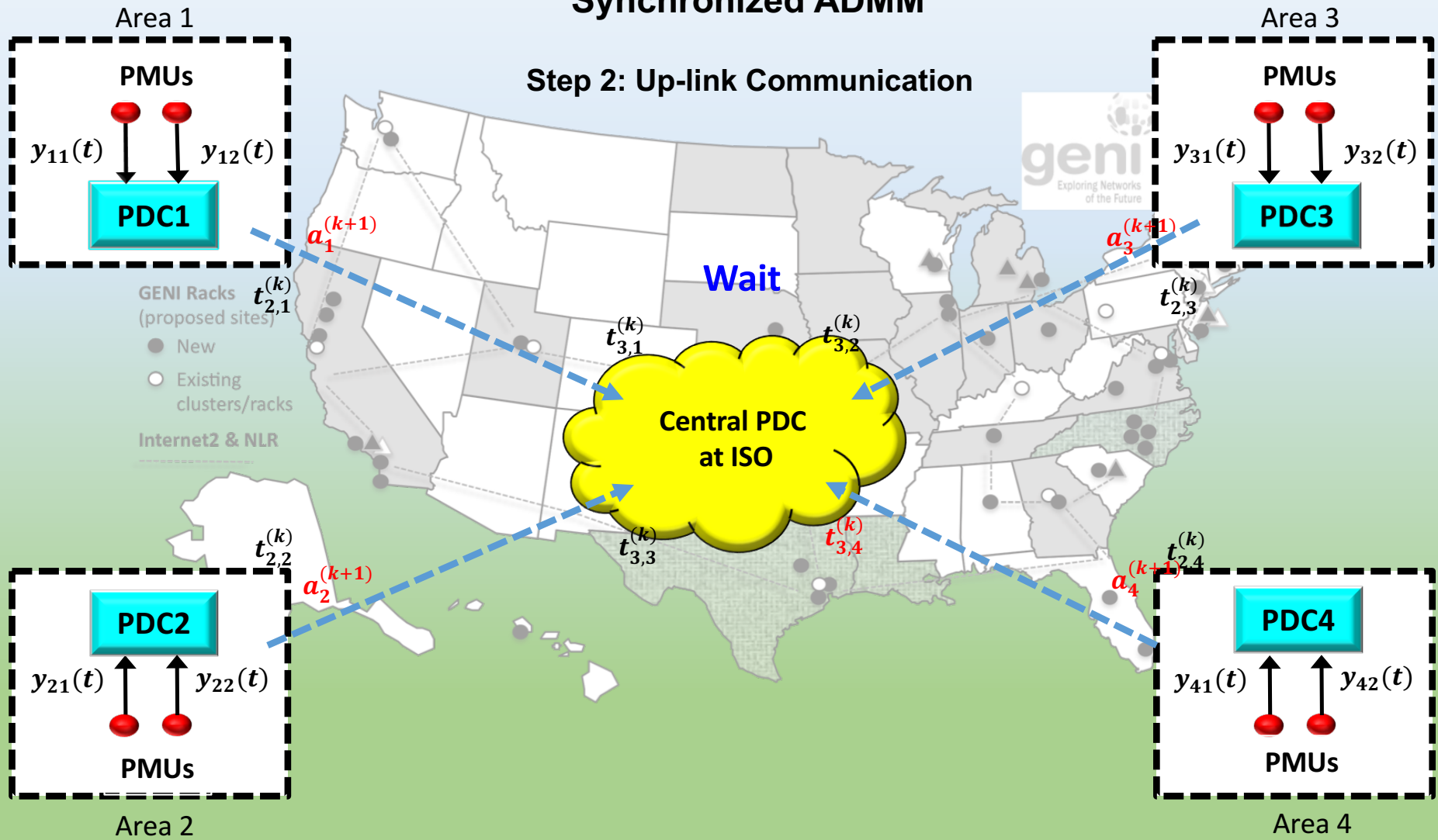
# Synchronized ADMM

## Step 1: Local Computation



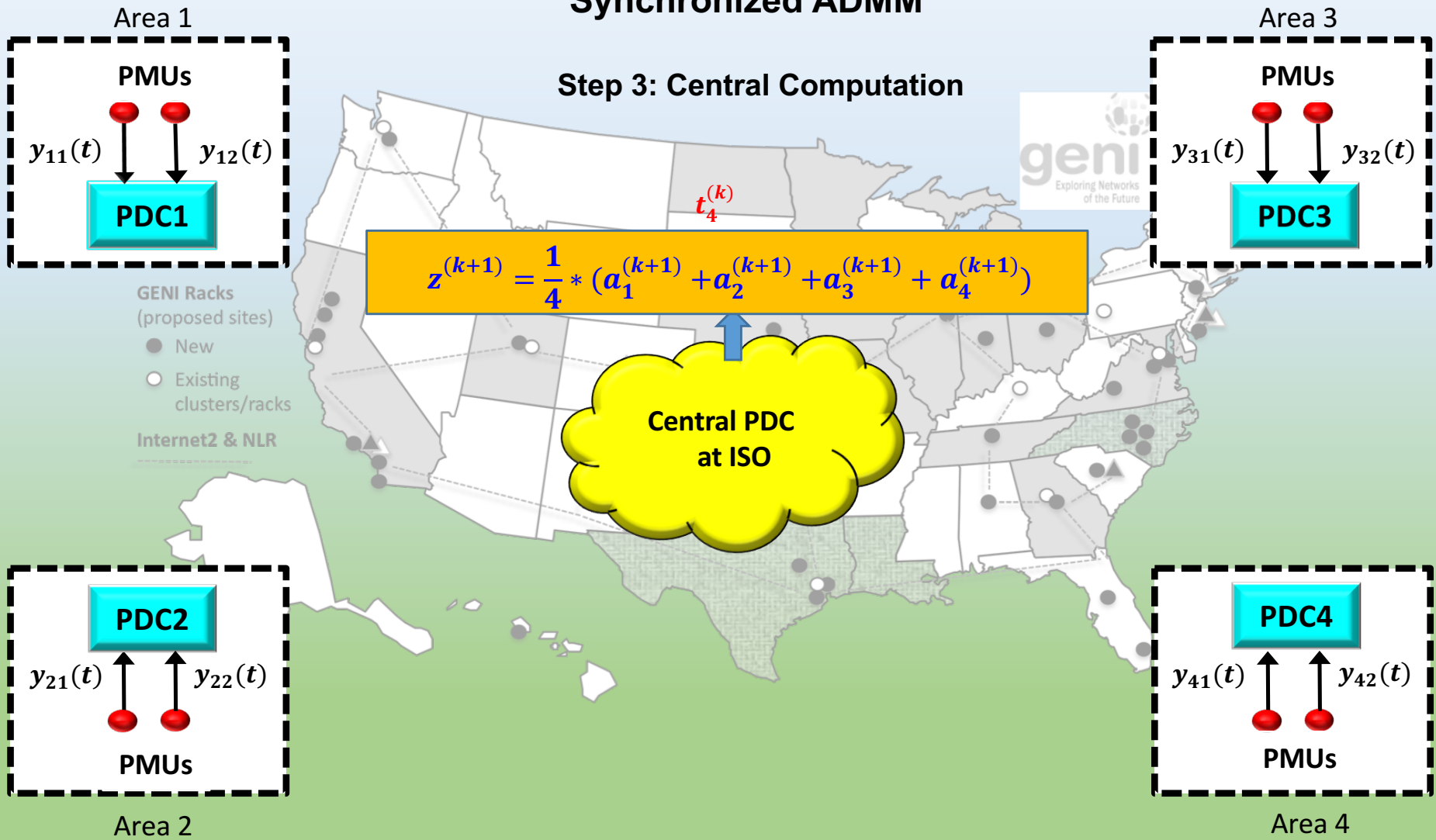
# Synchronized ADMM

## Step 2: Up-link Communication



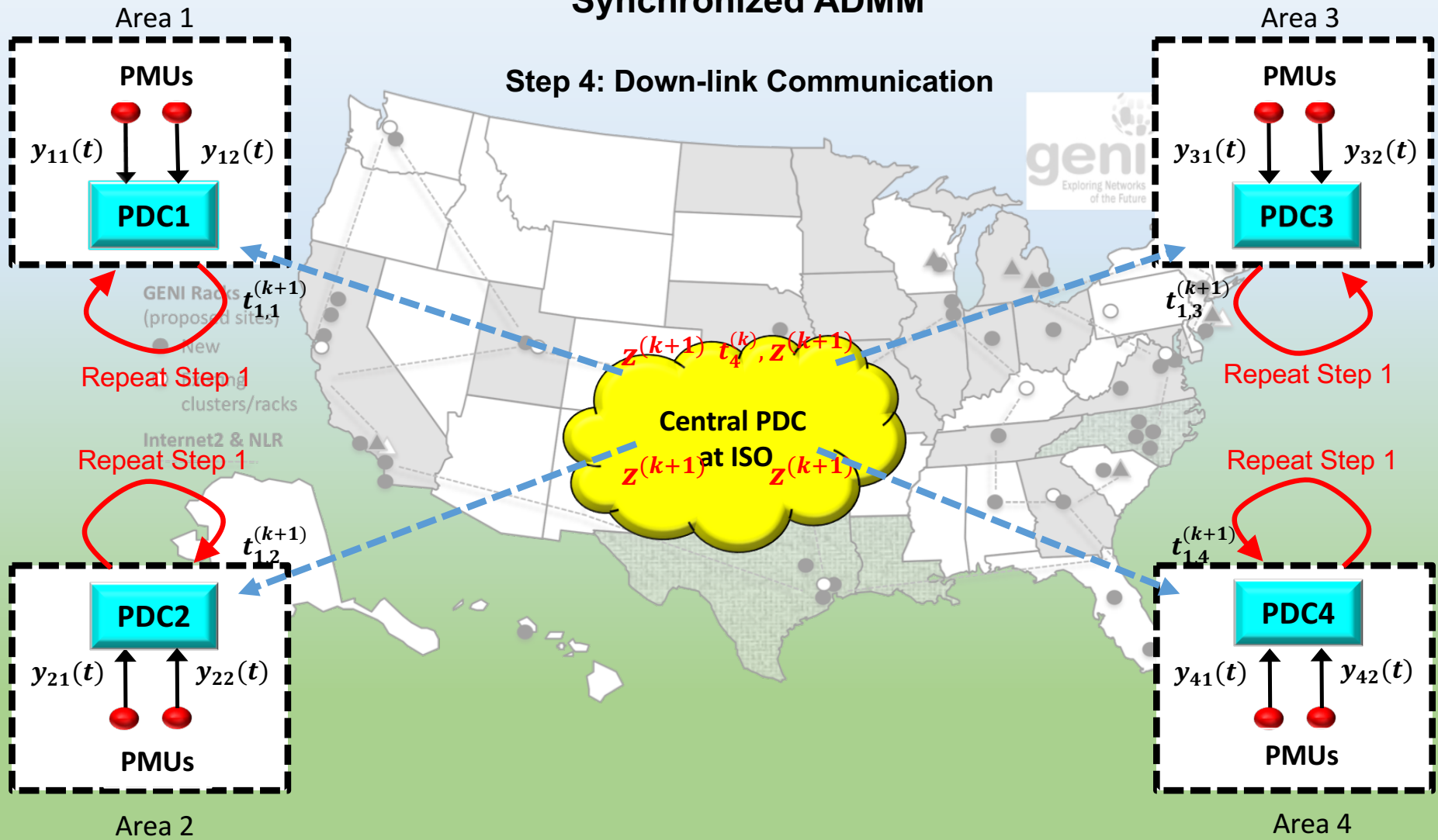
# Synchronized ADMM

## Step 3: Central Computation

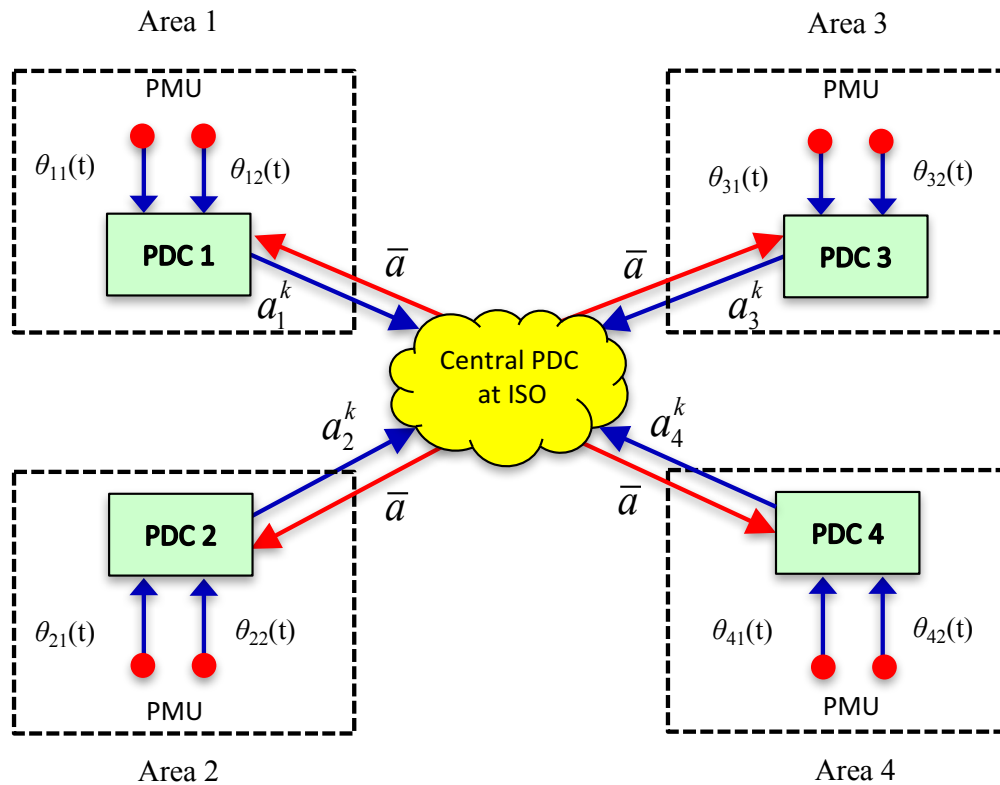


# Synchronized ADMM

## Step 4: Down-link Communication



# Cyber-Physical Coupling: Incorporating Asynchronous Wide-Area Communication



If a message doesn't arrive at ISO by a delay threshold  $d_1^*$

- **Strategy 1:**

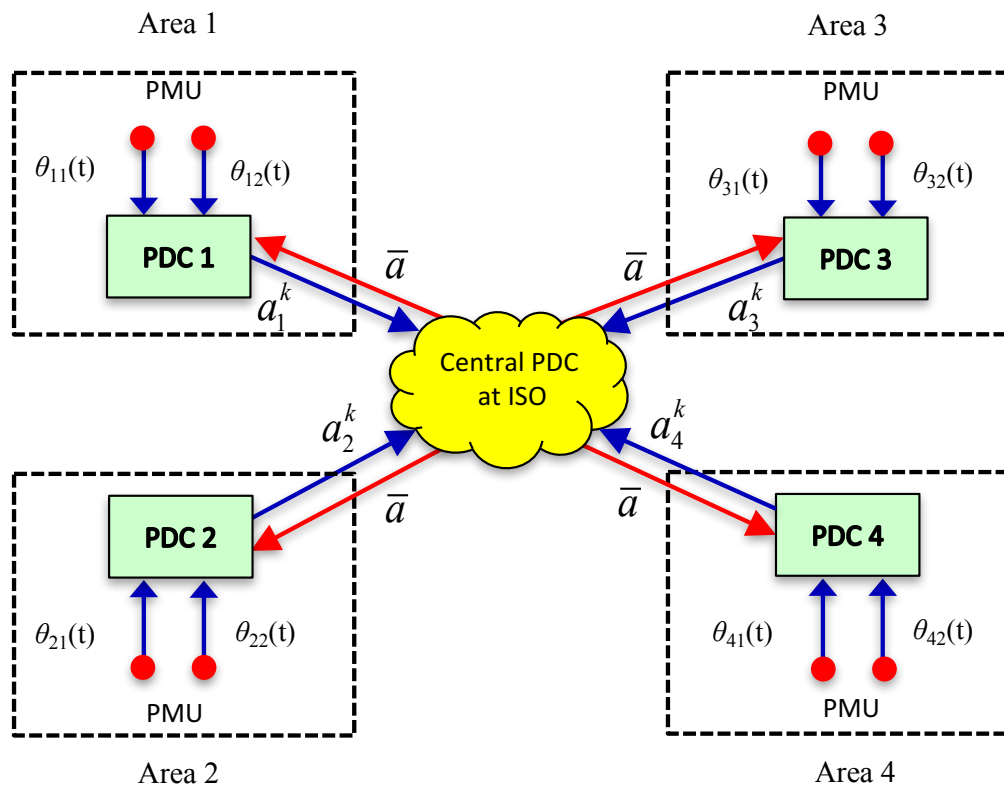
$$z^{(k+1)} = \frac{1}{|S_1^{(k)}|} \sum_{i \in S_1^{(k)}} (a_i^{(k+1)} + \frac{1}{\rho} w_i^{(k)})$$

→ **Can easily lead to divergence**

## Traffic Models for Internet Delays:

$$P(t) = \frac{1}{2} \left[ \operatorname{erf}\left(\frac{\mu}{\sqrt{2}\sigma}\right) + \operatorname{erf}\left(\frac{t-\mu}{\sqrt{2}\sigma}\right) \right] + \frac{(1-p)}{N} e^{\left(\frac{1}{2}\lambda^2\sigma^2 + \mu\lambda\right)} \left[ \operatorname{erf}\left(\frac{\lambda\sigma^2 + \mu}{\sqrt{2}\sigma}\right) + \operatorname{erf}\left(\frac{t - \lambda\sigma^2 - \mu}{\sqrt{2}\sigma}\right) \right]$$

# Cyber-Physical Coupling: Incorporating Asynchronous Wide-Area Communication



If a message doesn't arrive at ISO by a delay threshold  $d_1^*$

## • Strategy 2:

$$z^{(k+1)} = \frac{1}{N} \left( \sum_{i \in S_1^{(k)}} (a_i^{(k+1)} + \frac{1}{\rho} w_i^{(k)}) + \sum_{i \notin S_1^{(k)}} (a_i^{(k)} + \frac{1}{\rho} w_i^{(k-1)}) \right)$$



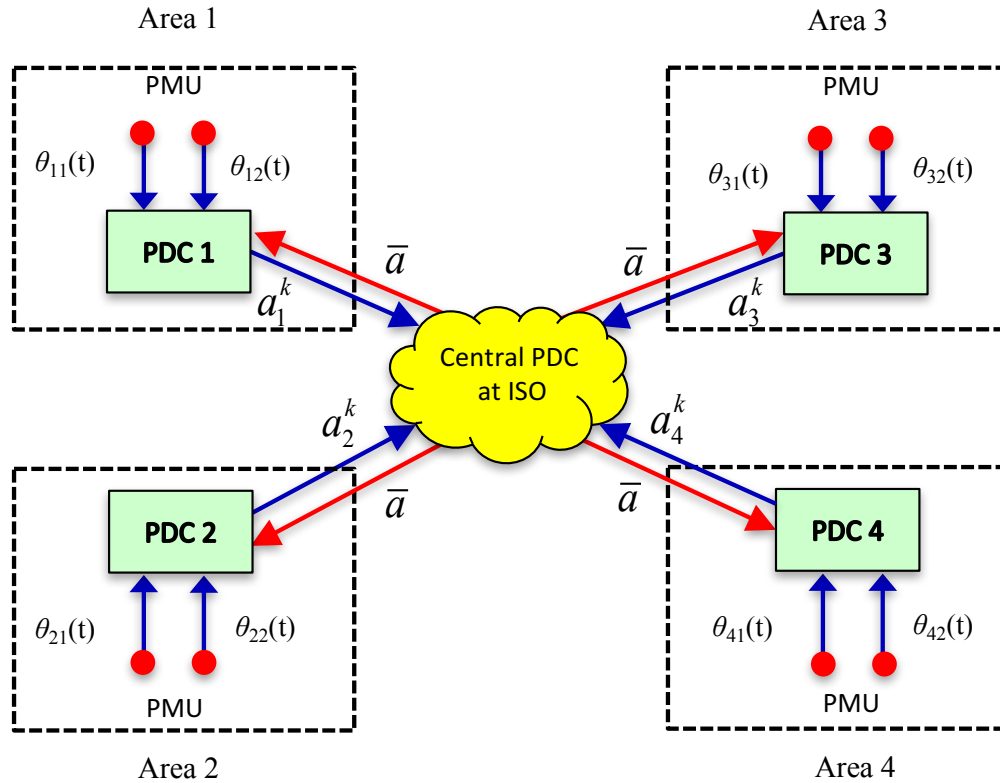
Substitute values from  
previous iteration

**Convergent, but slow**

## Traffic Models for Internet Delays:

$$P(t) = \frac{1}{2} \left[ \operatorname{erf}\left(\frac{\mu}{\sqrt{2}\sigma}\right) + \operatorname{erf}\left(\frac{t - \mu}{\sqrt{2}\sigma}\right) \right] + \frac{(1-p)}{N} e^{\left(\frac{1}{2}\lambda^2\sigma^2 + \mu\lambda\right)} \left[ \operatorname{erf}\left(\frac{\lambda\sigma^2 + \mu}{\sqrt{2}\sigma}\right) + \operatorname{erf}\left(\frac{t - \lambda\sigma^2 - \mu}{\sqrt{2}\sigma}\right) \right]$$

# Cyber-Physical Coupling: Incorporating Asynchronous Wide-Area Communication



- **Strategy 3: Keep a correlation log at central PDC**

$$C^k = \begin{bmatrix} \xi(a_1^k, a_1^k) & \xi(a_1^k, a_2^k) & \xi(a_1^k, a_3^k) & \xi(a_1^k, a_4^k) \\ \xi(a_2^k, a_1^k) & \xi(a_2^k, a_2^k) & \xi(a_2^k, a_3^k) & \xi(a_2^k, a_4^k) \\ \xi(a_3^k, a_1^k) & \xi(a_3^k, a_2^k) & \xi(a_3^k, a_3^k) & \xi(a_3^k, a_4^k) \\ \xi(a_4^k, a_1^k) & \xi(a_4^k, a_2^k) & \xi(a_4^k, a_3^k) & \xi(a_4^k, a_4^k) \end{bmatrix}$$

$$z^{(k+1)} = \frac{1}{N} \left( \sum_{i \in \mathcal{S}^{(k)}} (a_i^{(k+1)} + \frac{1}{\rho} w_i^{(k)}) + \sum_{i \notin \mathcal{S}^{(k)}} (a_j^{(k)} + \frac{1}{\rho} w_i^{(k-1)}) \right)$$

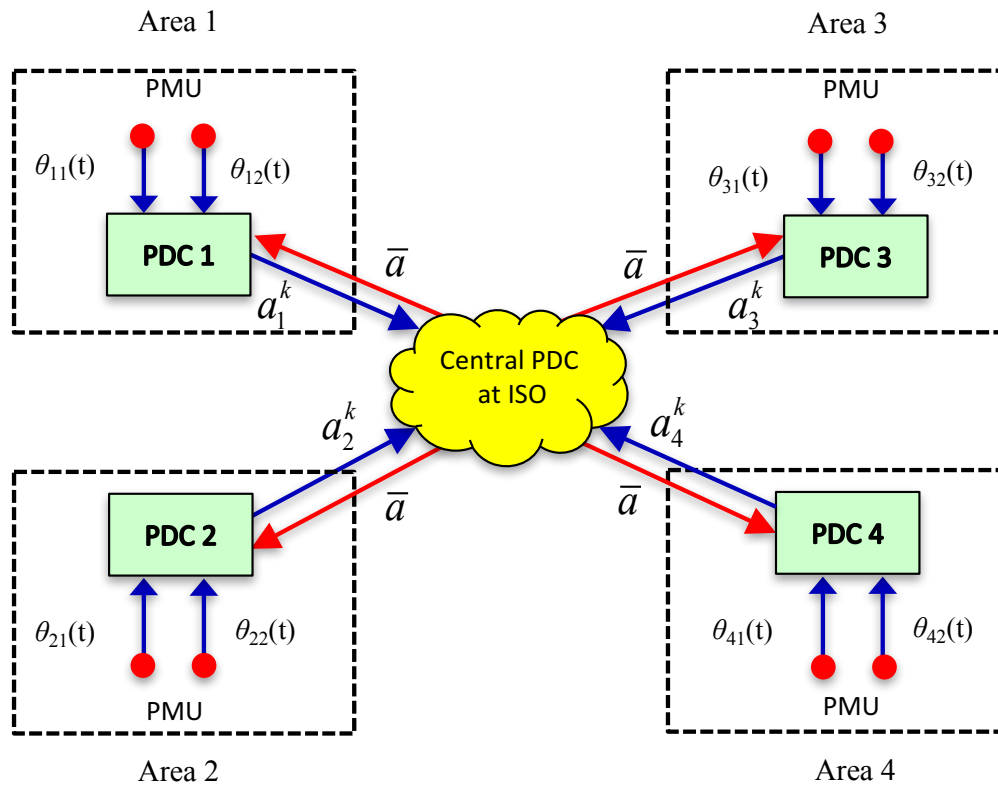
↑  
Substitute value of iterate with highest correlation from previous iteration

## Traffic Models for Internet Delays:

$$P(t) = \frac{1}{2} \left[ \operatorname{erf}\left(\frac{\mu}{\sqrt{2}\sigma}\right) + \operatorname{erf}\left(\frac{t-\mu}{\sqrt{2}\sigma}\right) \right] + \frac{(1-p)}{N} e^{\left(\frac{1}{2}\lambda^2\sigma^2 + \mu\lambda\right)} \left[ \operatorname{erf}\left(\frac{\lambda\sigma^2 + \mu}{\sqrt{2}\sigma}\right) + \operatorname{erf}\left(\frac{t - \lambda\sigma^2 - \mu}{\sqrt{2}\sigma}\right) \right]$$



# Cyber-Physical Coupling: Incorporating Asynchronous Wide-Area Communication



## • Open questions:

1. Both waiting and not waiting for a delayed packet impacts overall convergence time

When to wait, and when not to wait?

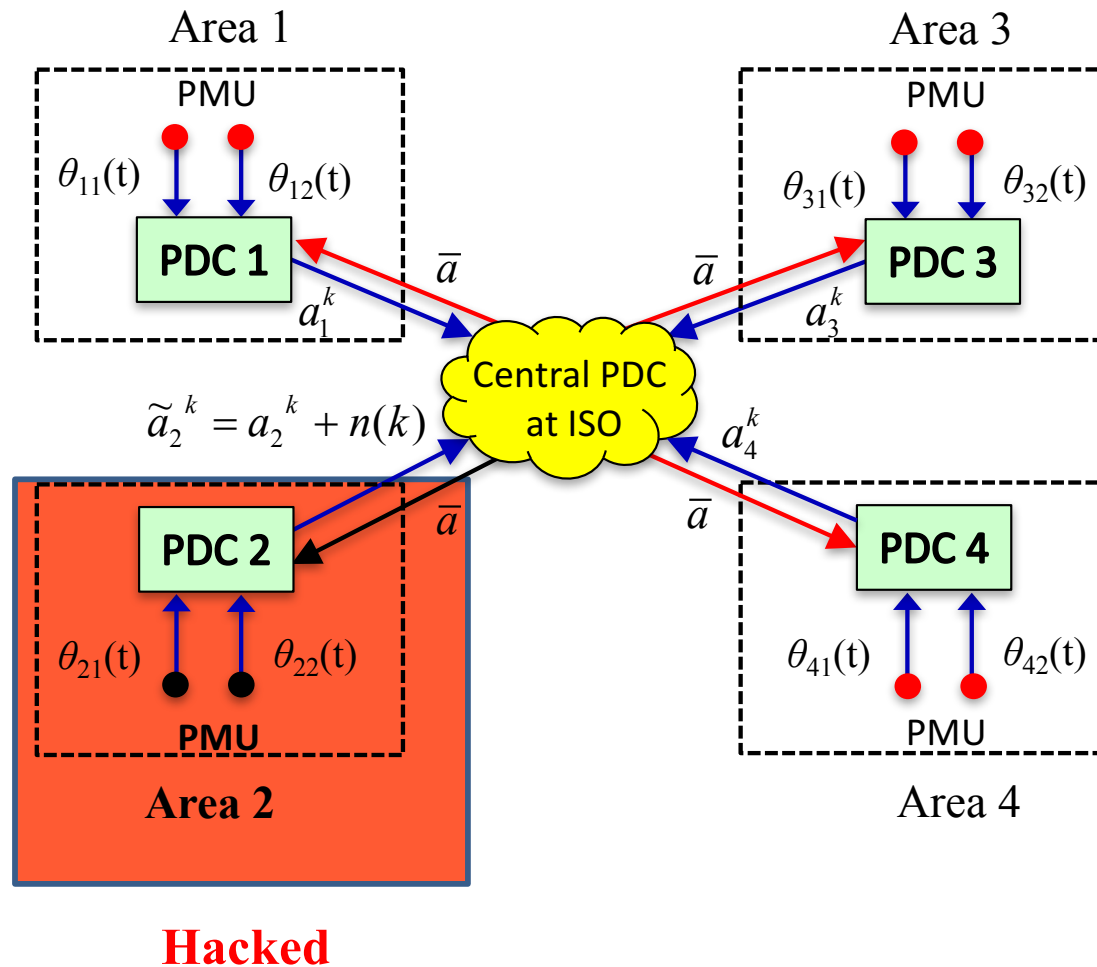
2. Co-designing the communication network using software-defined network (SDN) principles

Minimize delay in each link while other processes are running in the cloud (resource allocation problem)

## Traffic Models for Internet Delays:

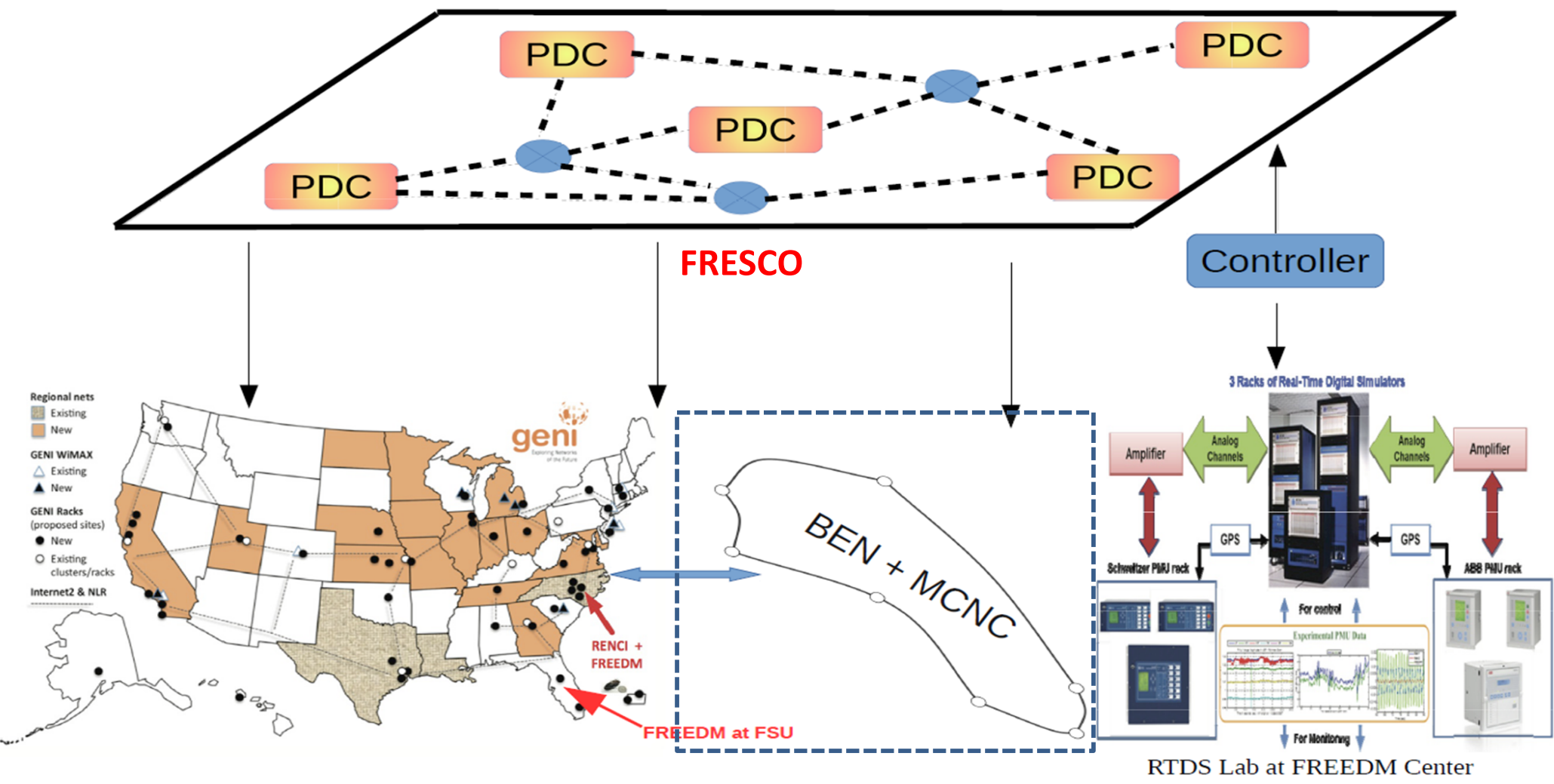
$$P(t) = \frac{1}{2} \left[ \operatorname{erf}\left(\frac{\mu}{\sqrt{2}\sigma}\right) + \operatorname{erf}\left(\frac{t - \mu}{\sqrt{2}\sigma}\right) \right] + \frac{(1-p)}{N} e^{\left(\frac{1}{2}\lambda^2\sigma^2 + \mu\lambda\right)} \left[ \operatorname{erf}\left(\frac{\lambda\sigma^2 + \mu}{\sqrt{2}\sigma}\right) + \operatorname{erf}\left(\frac{t - \lambda\sigma^2 - \mu}{\sqrt{2}\sigma}\right) \right]$$

# Detecting Malicious Data-Manipulators



- Correct values of  $a_1^k$ ,  $a_3^k$ ,  $a_4^k$  are communicated to the ISO
- But incorrect value of  $a_2^k$   $\tilde{a}_2^k = a_2^k + n(k)$  is communicated, ISO does not know that this is incorrect
- Trajectories of the estimates will start diverging as the bias excites the consensus eigenvalue

# ExoGENI-WAMS Testbed at NC State & RENCI/UNC Chapel Hill

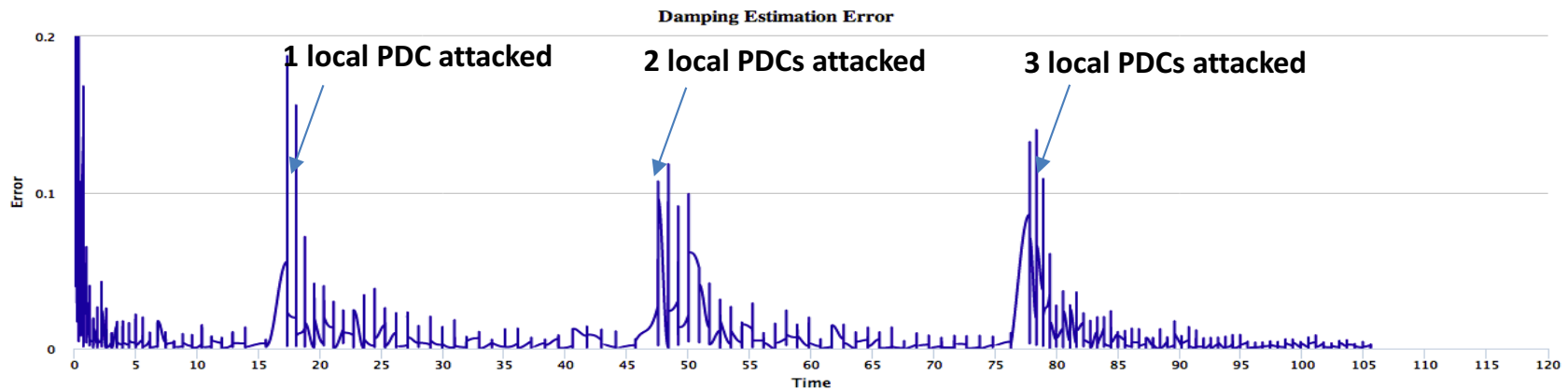
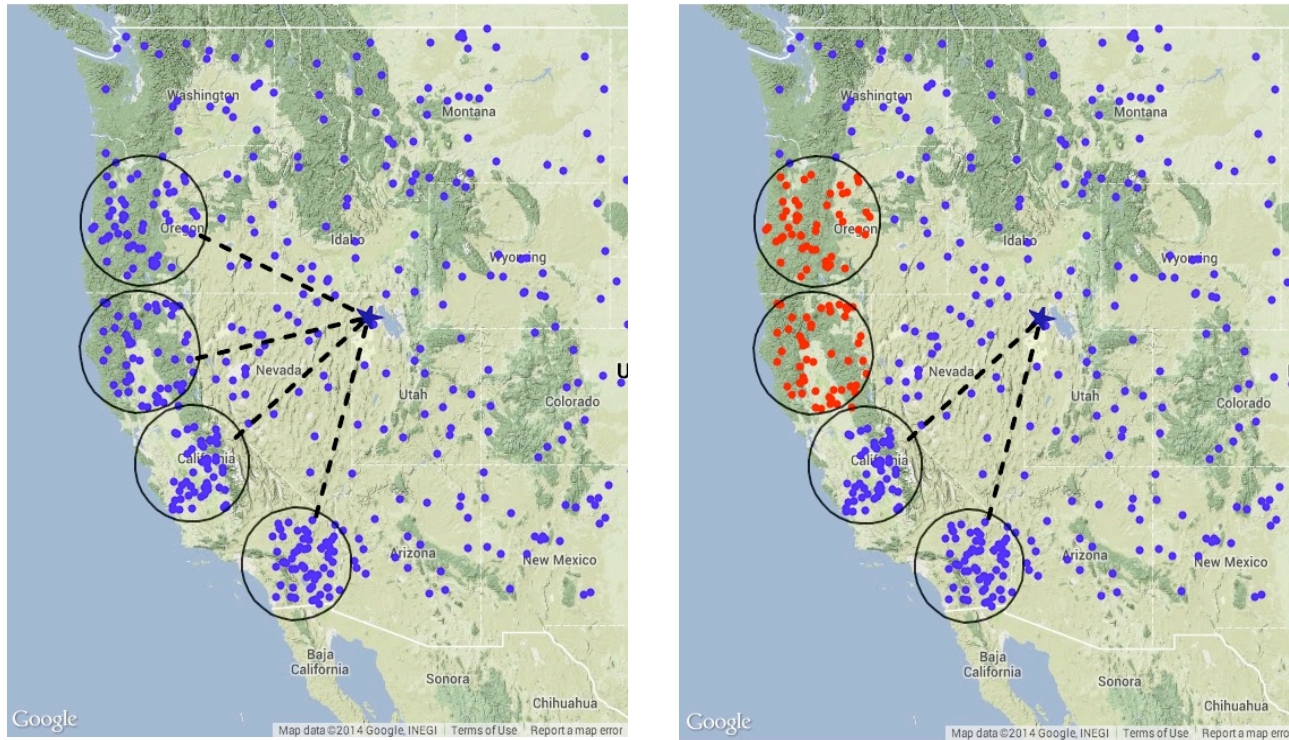


**Middleware provided by Green Energy Corporation and RTI**

# Experimental Validation on Federated Testbeds

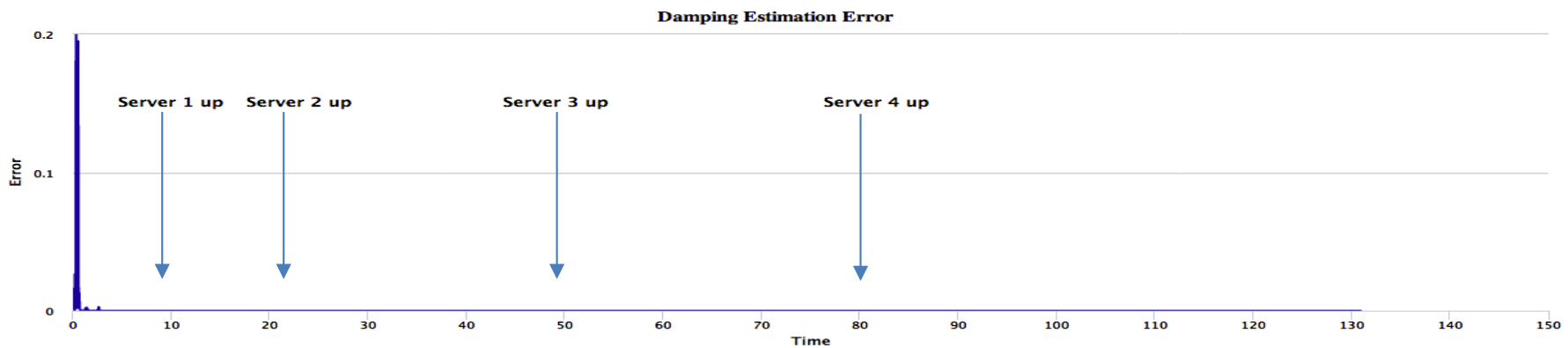
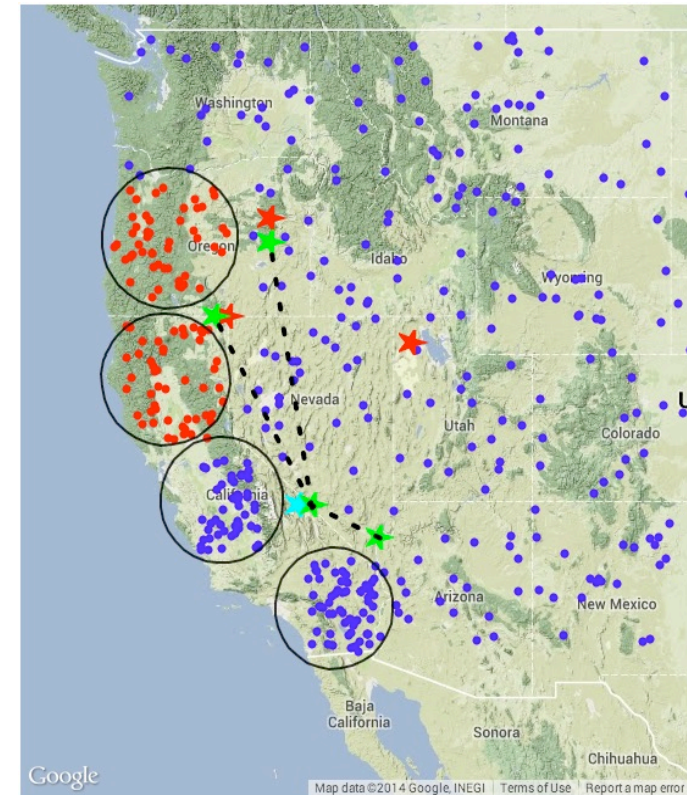
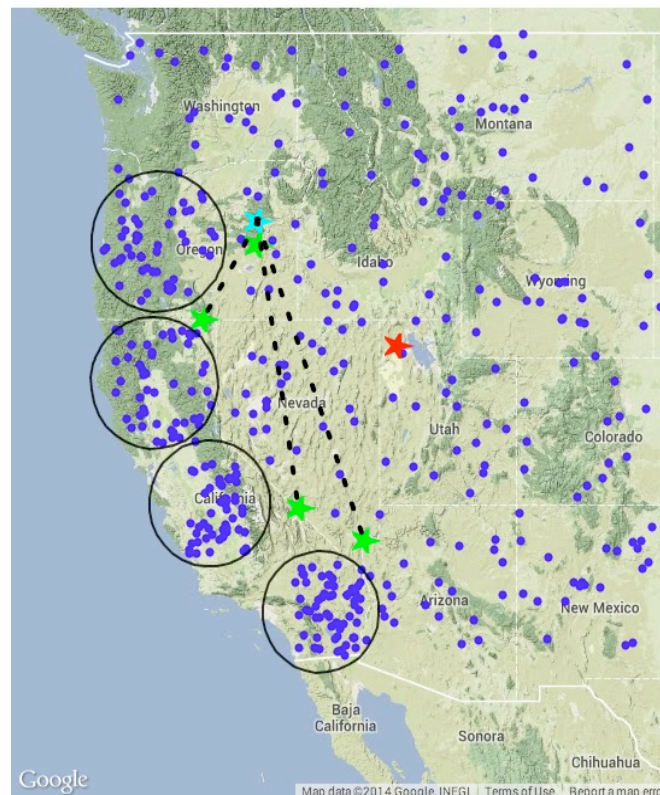
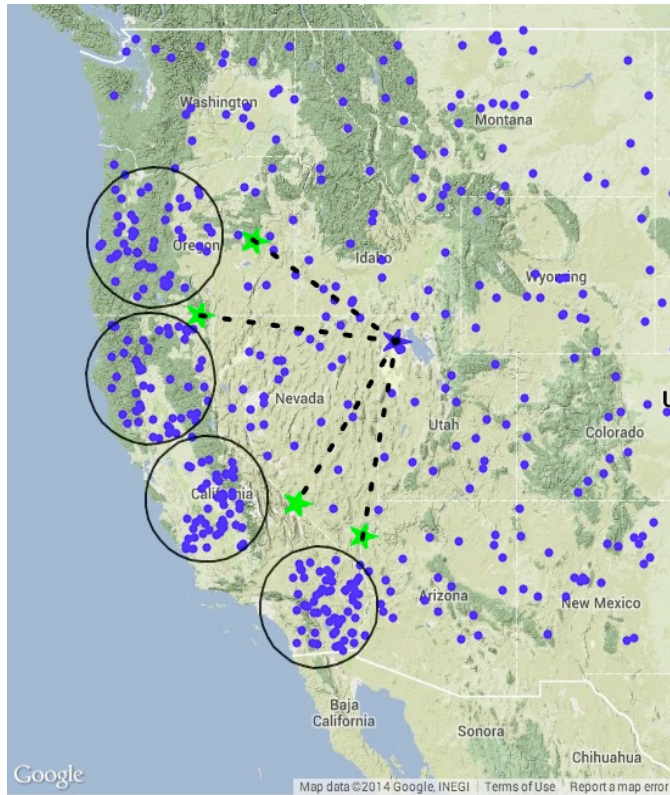
**Federated Testbeds:** *RTDS Lab of NC State + DETER Lab of Univ. of South California*

## Centralized Architecture



# Experimental Validation on Federated Testbeds

## Distributed Architecture

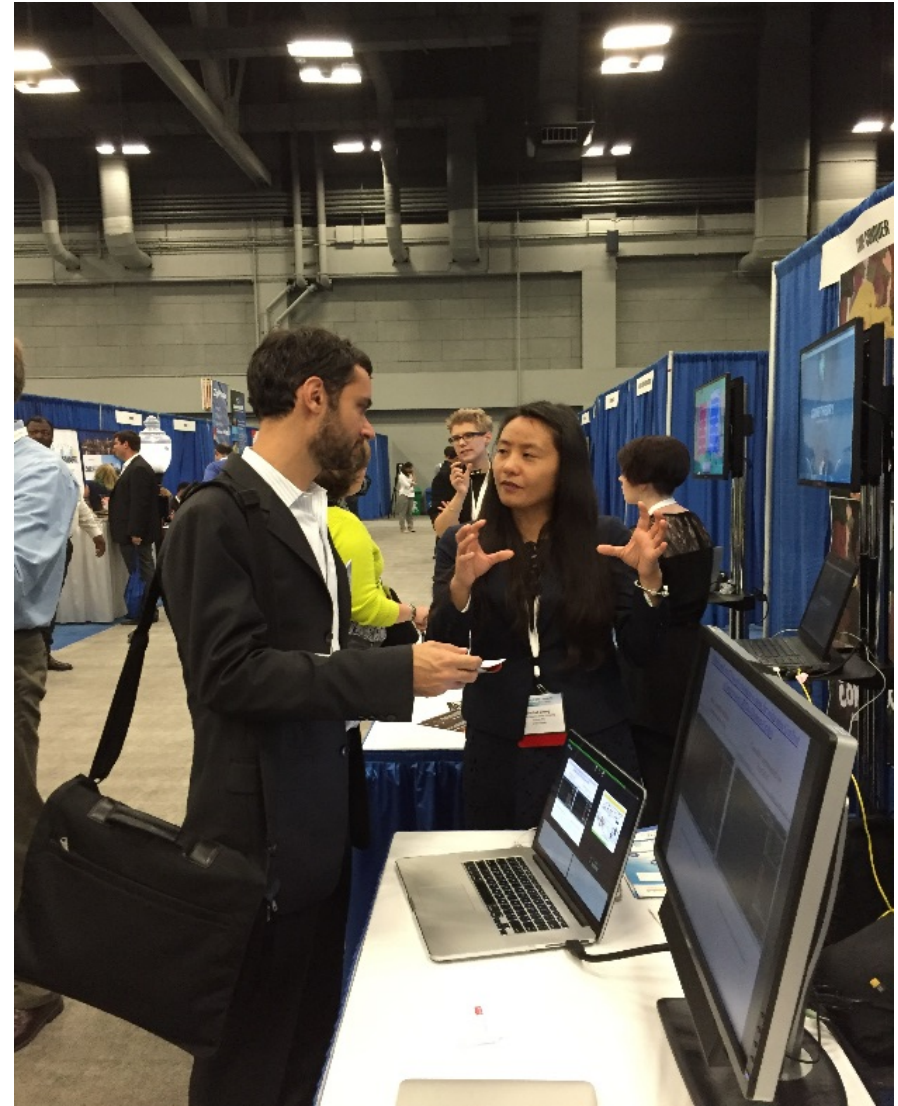


# Project Demos:



DETER Demo at Smart-America 2014

Best Energy App Award at US Ignite 2015



US Ignite & NIST  
Smart Cities Application  
Summit, Austin, TX, 2016

# ExoGENI-WAMS Testbed

Bring Concepts of **Cloud Computing** and **Software Defined Networking** into Research of Wide-Area Monitoring and Control with PMU data

- **Wide-Area Monitoring and Control is a typical cyber-physical system**
- **Problems of the physical subsystem**
  1. *Accessing of real PMU measurements due to **privacy and non-disclosure issues***
  2. *Not sufficient for studying dynamics of the entire system due to **limited coverage***
- **Requirements of the cyber subsystem**

*To utilize next-generation cyber-infrastructure technologies:*

  1. *high-speed virtual networking*
  2. *high performance networked cloud computing*
  3. *virtualization and data management*

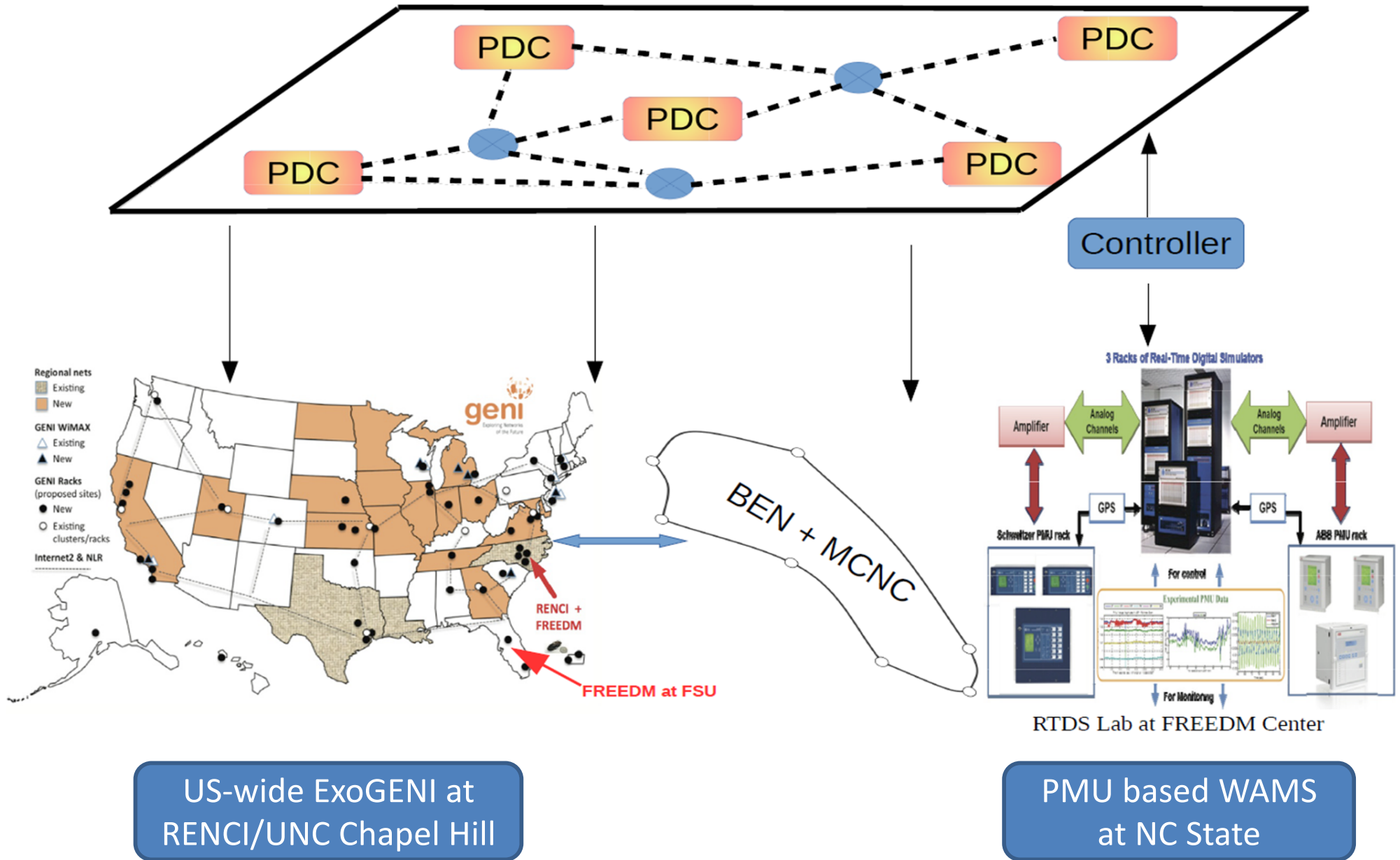
**Objective:** *build up a perfect cyber-physical testbed for WAMS research*

**Result: ExoGENI-WAMS Testbed**

*Physical subsystem – Hardware-In-Loop Framework (RTDS + PMU-based WAMS)*

*Cyber subsystem – Networked Cloud Computing Platform (ExoGENI)*

# Architecture of ExoGENI-WAMS Testbed



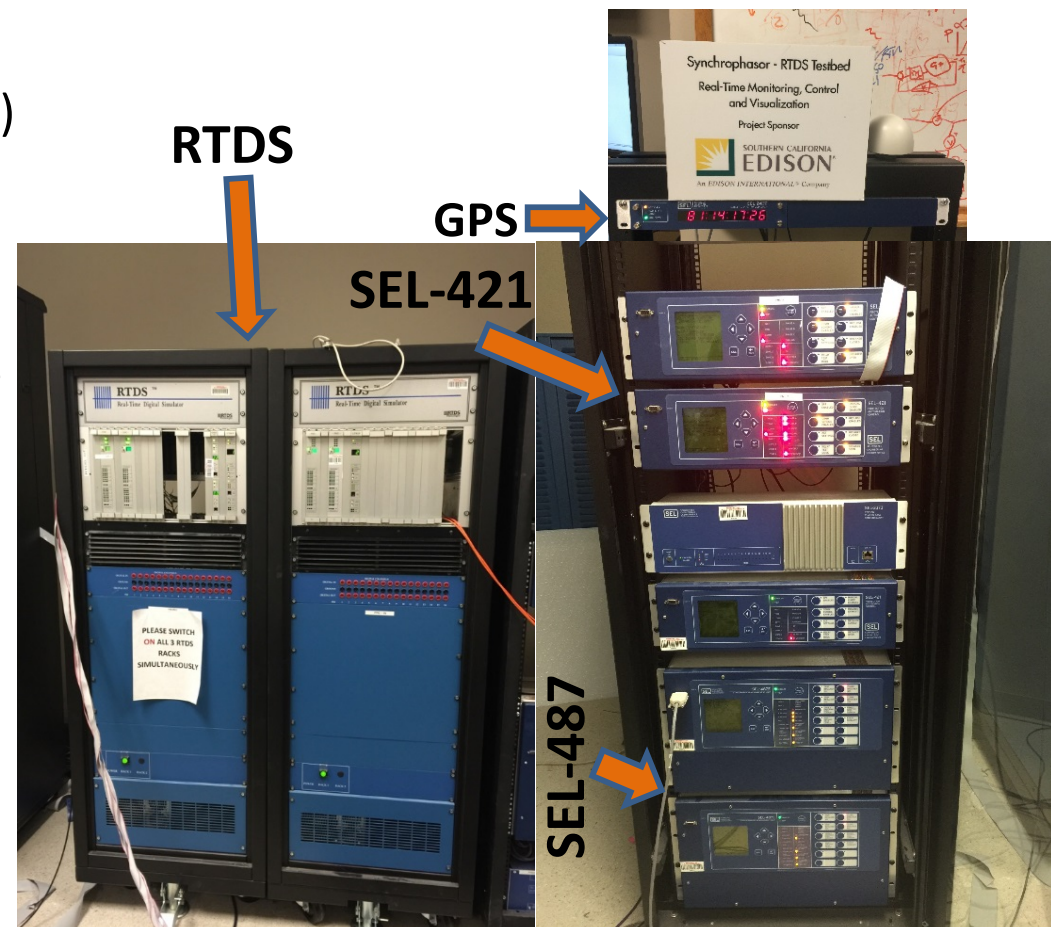
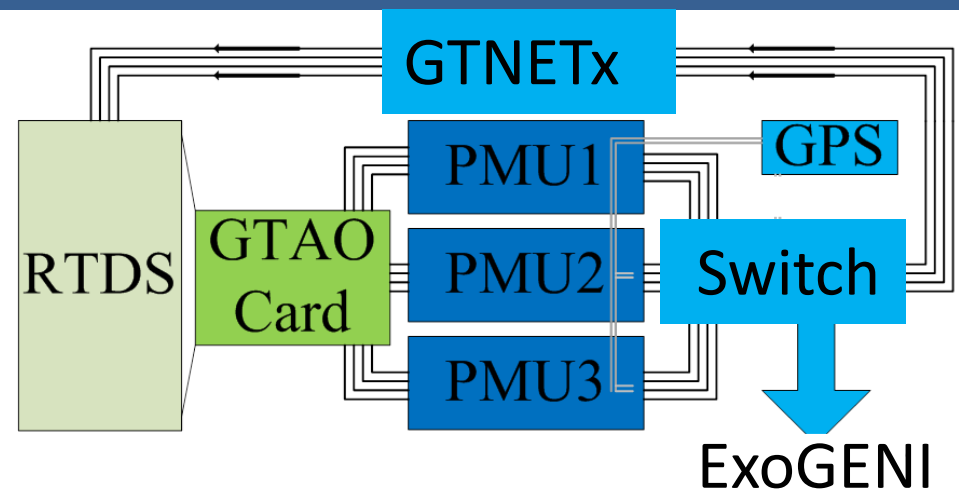


# Components: RTDS-PMU based WAMS

**RTDS** – two racks, 50 us of time step,  
RSCAD – software to develop models for the RTDS to simulate  
GATO – hardware interface of Gigabit Transceiver Analog Output to generate voltage and current waveforms to the PMUs  
GTNETx2 – Gigabit Transceiver Network interface card to communicate with remote station. Multiple protocols (TCP socket, DNP, ...) IEEE 754 floating-point and integer type.

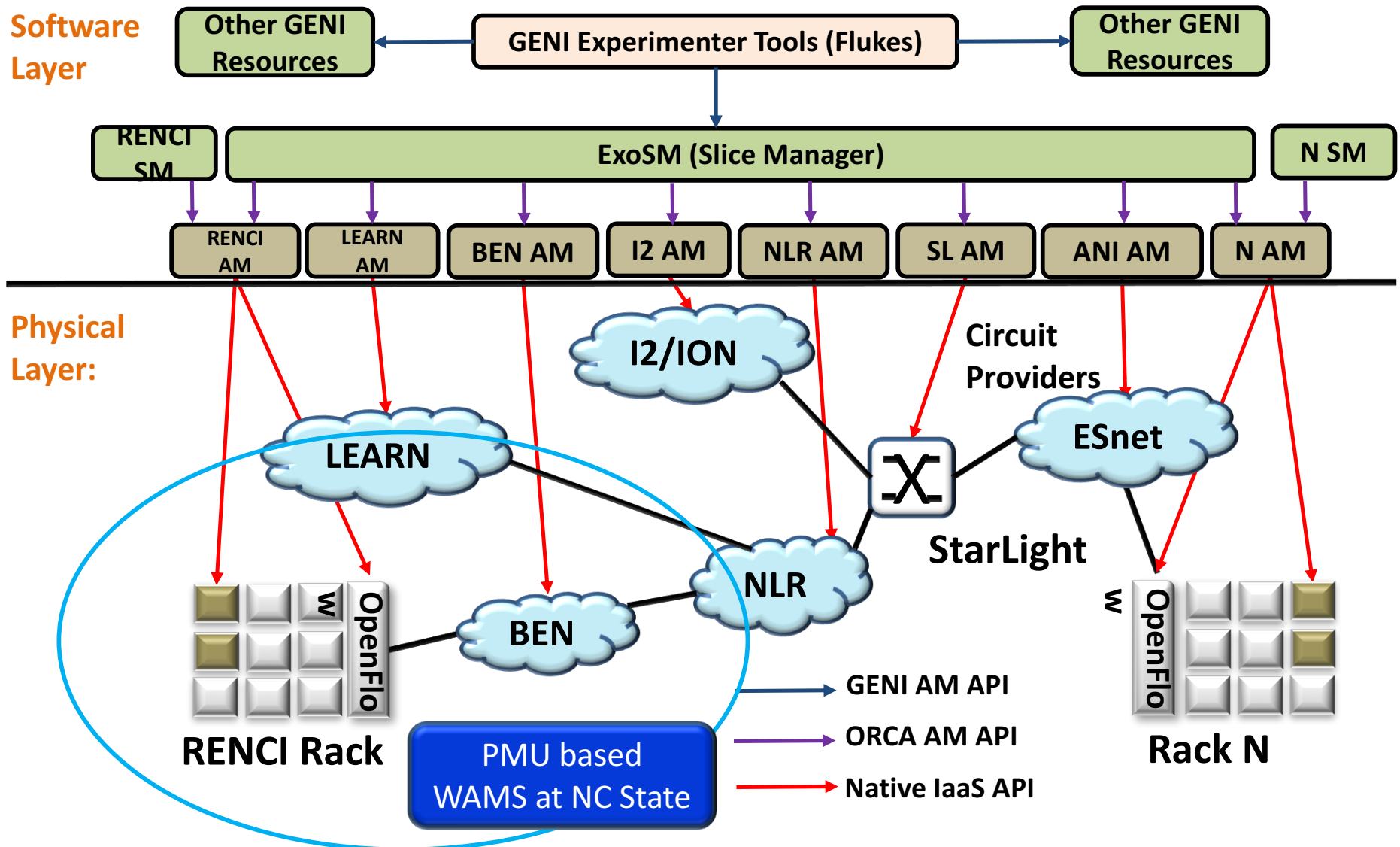
**PMU** – 5 units: 3 SEL-421 & 2 SEL-487  
Functions: accepting IRIG-B signal for satellite synchronization

**GPS** – SEL-2407 Satellite-Synchronized Clock



# Networked Cloud Computing Testbed – ExoGENI

ExoGENI provides in virtual IaaS services for innovative research on distributed applications for Wide-Area Monitoring and Control (14 rack sites at universities & labs over the US)



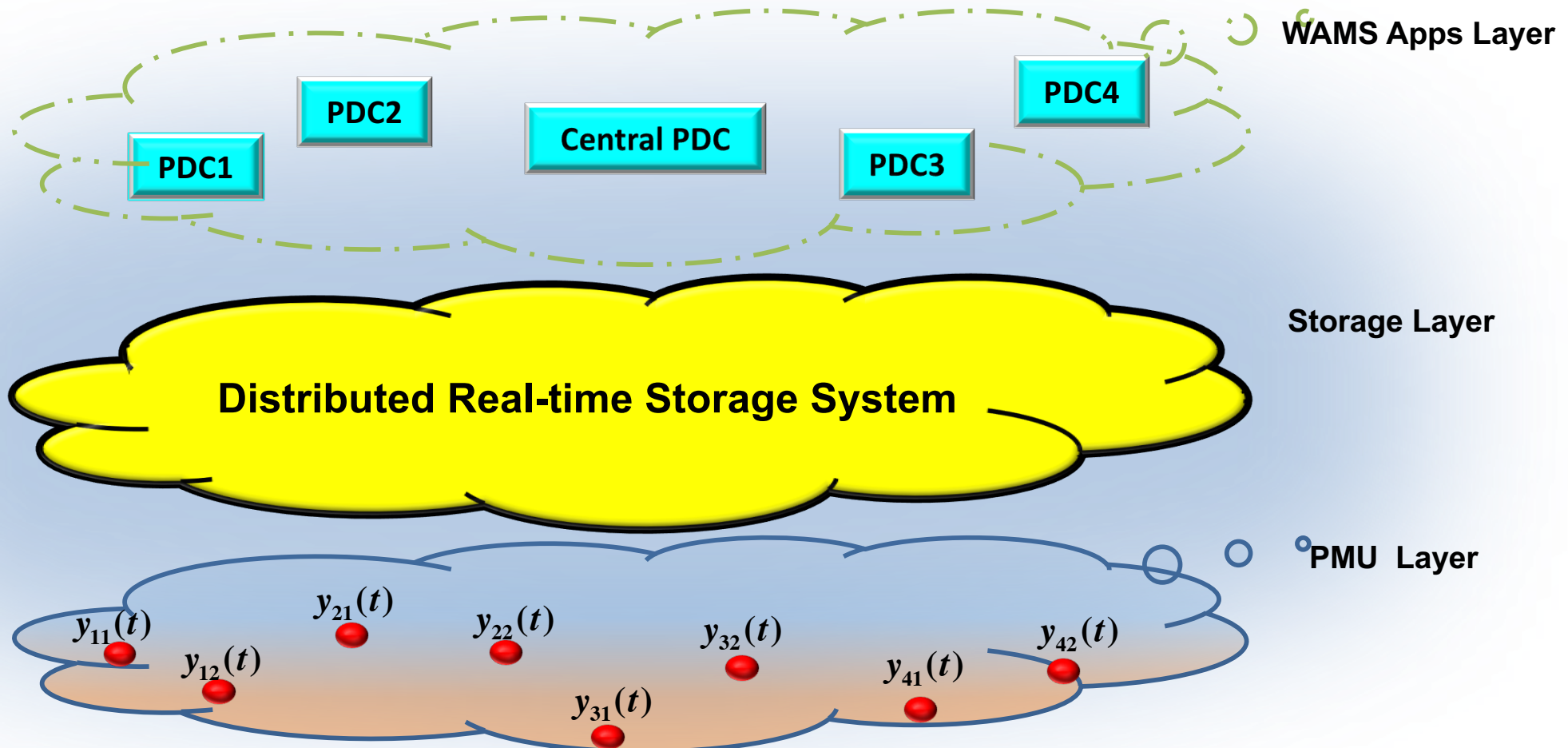
# Validations of ExoGENI-WAMS testbed

- **Visualization of Power Grid**
- **Delay Evaluation of CLS, DLS and RLS**
- **Distributed Oscillation Monitoring Algorithm**
- **Distributed Storage System (DSS) for Multiple Applications**
- **Distributed Control Algorithm**

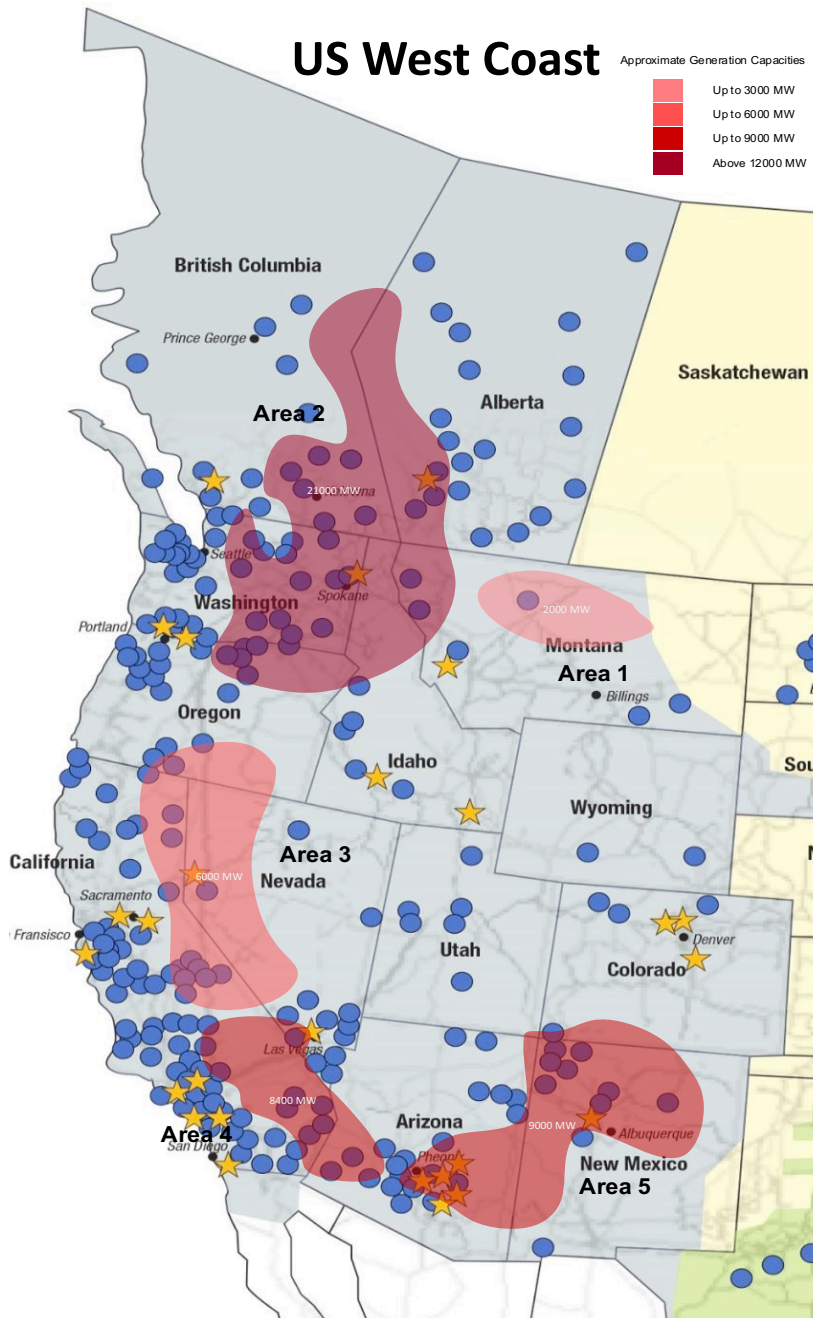
# Case Study I — Distributed Storage System with S-ADMM

## Synchronized ADMM + Storage System

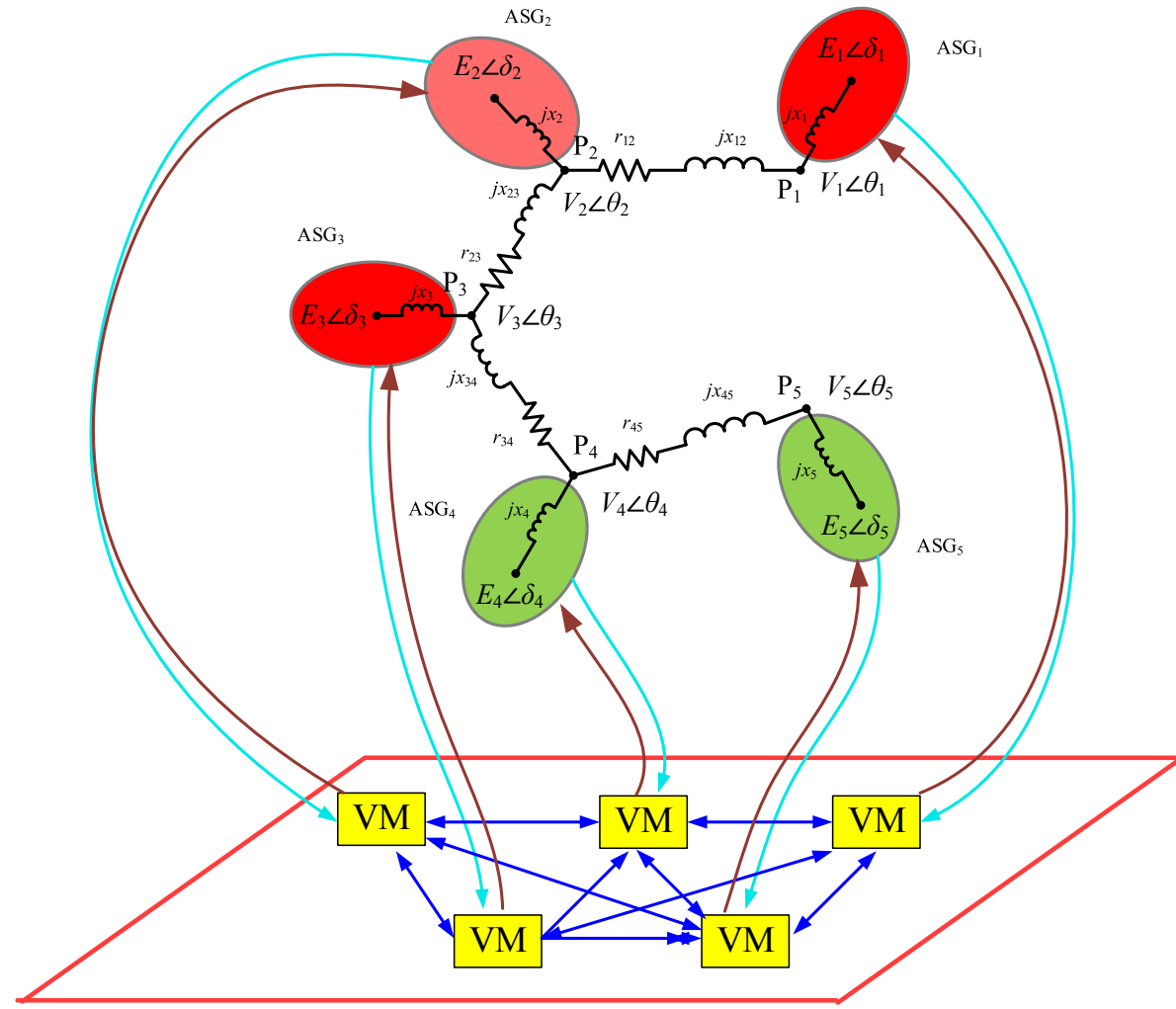
Step 1: PMUs keep storing data into Storage System



# Case Study II - Distributed Control Algorithm



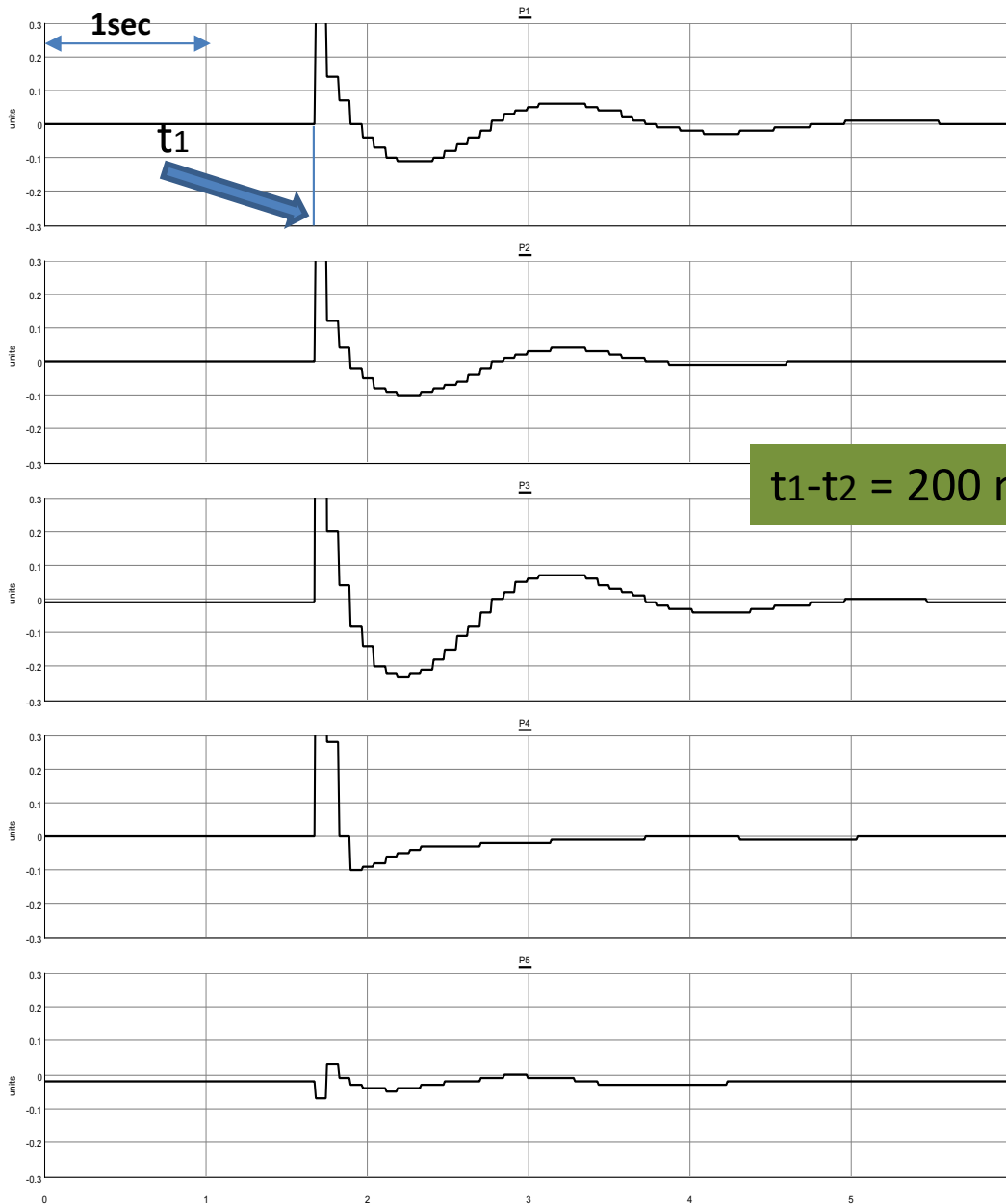
Close the loop from cloud to grid



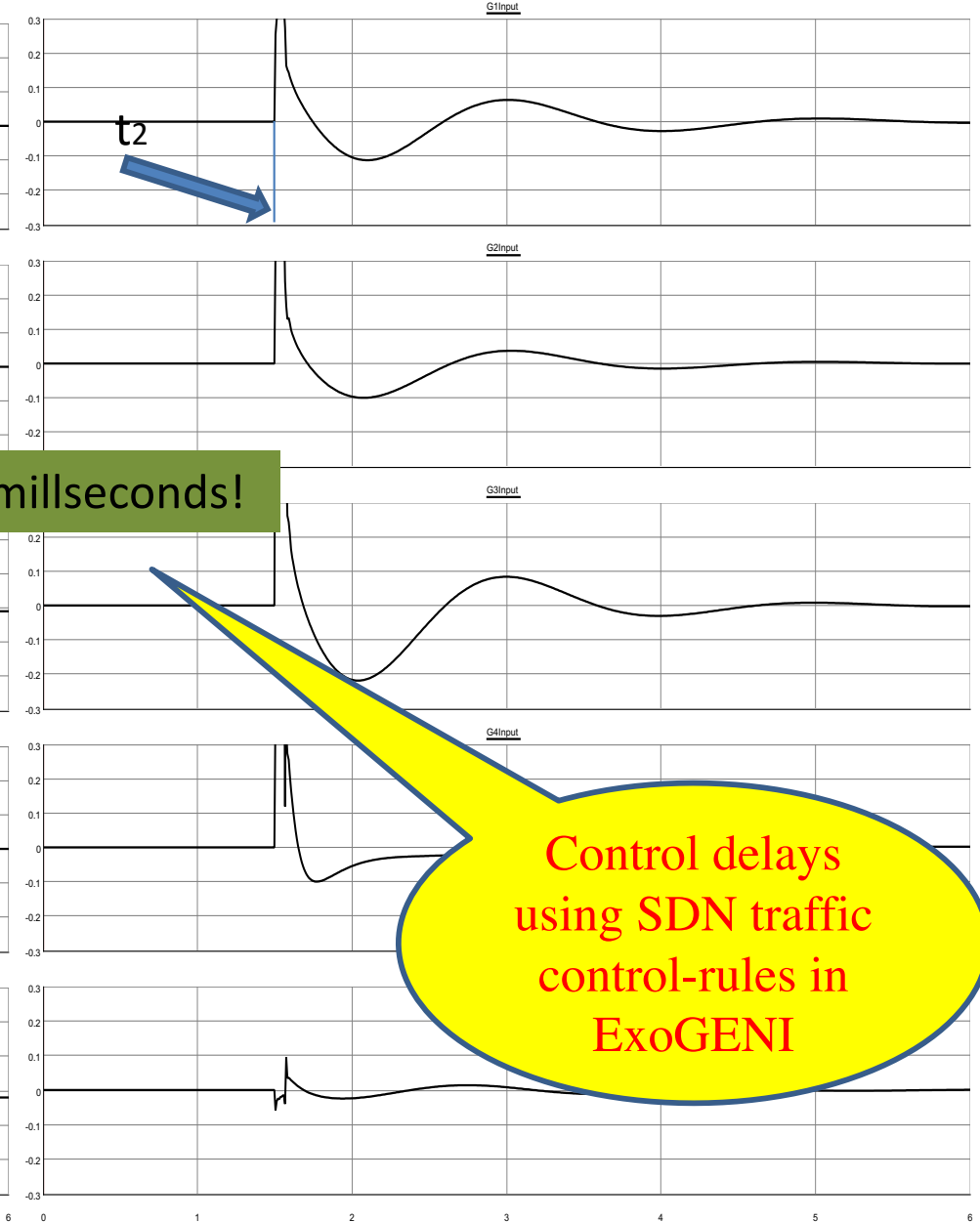
Third-Party Private Cloud  
+ Controllable Network

# Implementation of Distributed Control Algorithm

## Control Signals from ExoGENI



## Control Signals from RSCAD

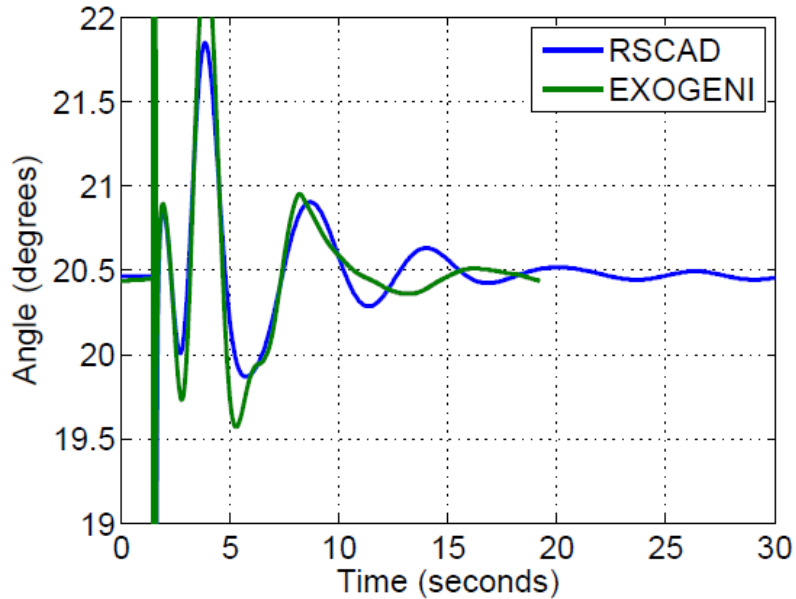


t1-t2 = 200 milliseconds!

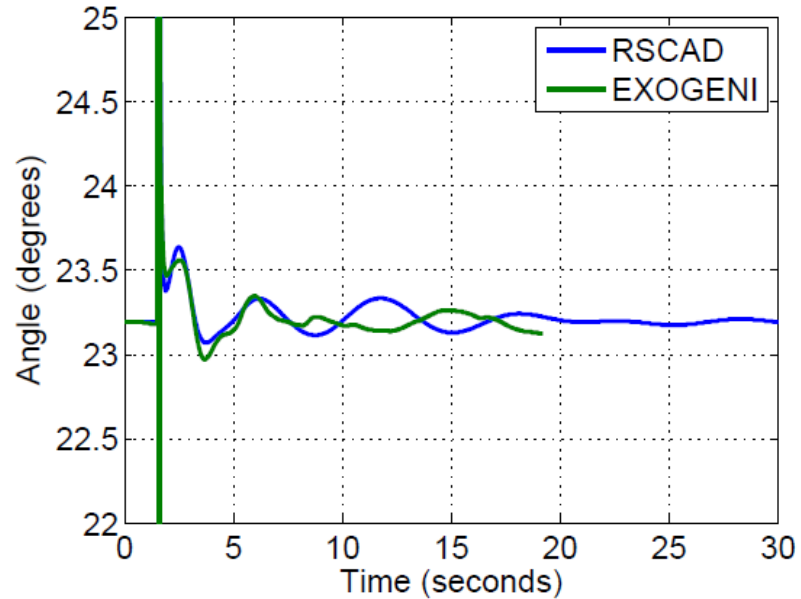
Control delays  
using SDN traffic  
control-rules in  
ExoGENI

# Comparison of Controller Performance

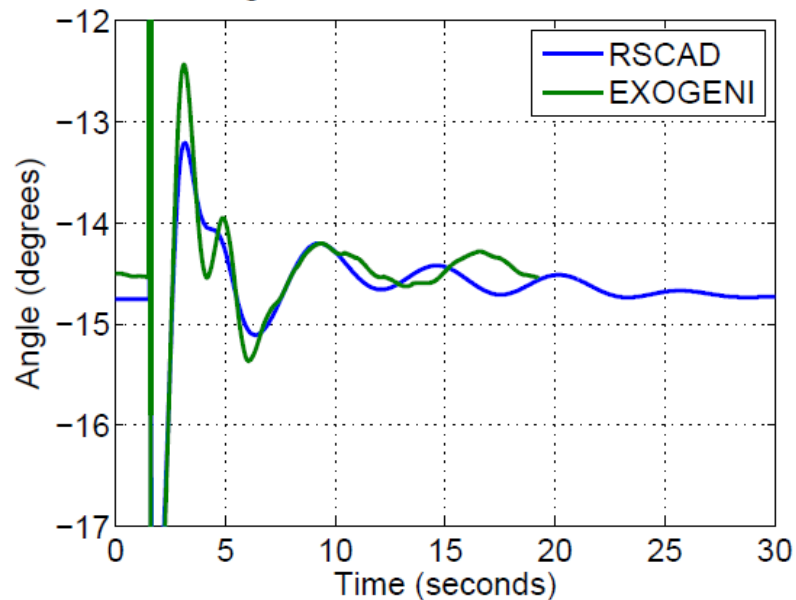
Angle Between Machines 1 and 2



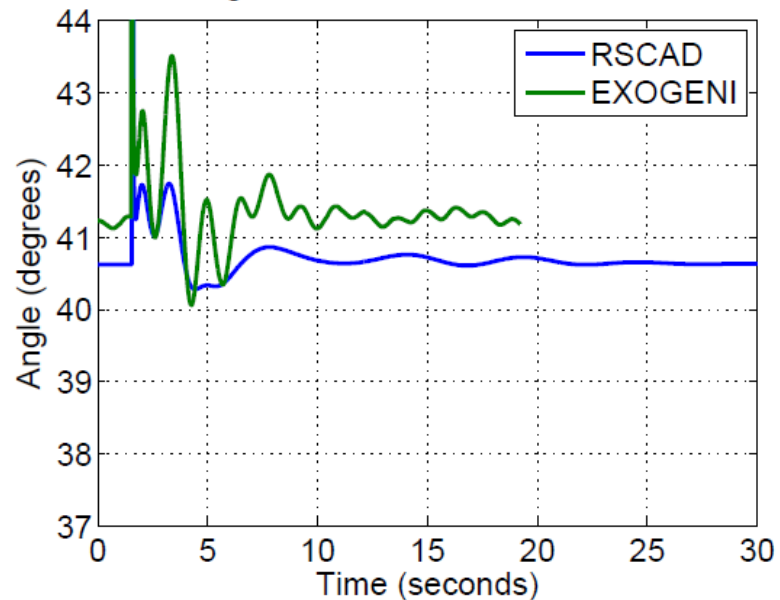
Angle Between Machines 2 and 3



Angle Between Machines 4 and 3



Angle Between Machines 5 and 4



Performance of offline controller compared against a cloud-computing implementation using the ExoGENI Network.

## **Summary of Experiments done so far:**

- Develop distributed delay-robust algorithms for wide-area oscillation mode monitoring of power systems
- Investigate the convergence performance of these distributed algorithms on delay distribution parameters and different variants of asynchronous strategies
- ExoGENI-WAMS-DETER testbed federation
- Validations of these distributed architecture using distributed cloud computing

## **Ongoing & Future Work with GENI & Internet2**

- Investigate the scalability of distributed algorithms
- Resilience and Cyber-security of ExoGENI using SDN principles
- Delay management in ExoGENI using SDN principles



# Conclusions

1. WAMS is a tremendously promising technology for control researchers
2. Control + Communications + Computing must merge
3. Plenty of new research problems – EE, Applied Math, Computer Science
4. Plenty of new control engineering problems
5. Right time to think mathematically – Network theory is imperative
6. Right time to pay attention to the bigger picture of the electric grid
7. Needs participation of young researchers!
8. Promises to create jobs and provide impetus to power engineering



# Thank You

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